

# Two sided shifts

$\mathbb{Z}$

- $\Sigma_n = \{ \underline{s} : \underline{s} = \dots s_{-1} s_0 s_1 s_2 \dots \} = \{ \underbrace{0, 1}_{n-1} \}^{\mathbb{Z}}$

- $\sigma : \Sigma_n \rightarrow \Sigma_n$

$$\sigma(\underline{s}) = \dots s_{-2} s_{-1} s_0 s_1 s_2 \dots$$

is now a homeomorphism -

is now close if  $s_l = t_l$  for  $|l| < N$  large  $N$

- $\underline{s}, \underline{t}$  are now close if  $s_l = t_l$  for  $|l| < N$  large  $N$

so middles are the same

$$\frac{|s_k - t_k|}{|k|}$$

metric in  $\Sigma_n$

- $d(\underline{s}, \underline{t}) = \sum_{k \in \mathbb{Z}} \frac{|s_k - t_k|}{|k|}$

- Now cylinder sets specify where ray starts

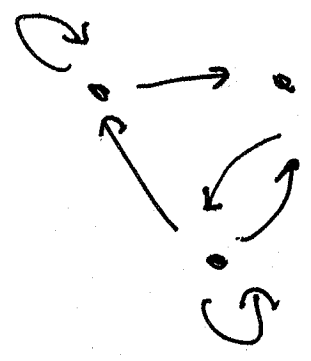
- $[b]_k = \{ \underline{s} \in \Sigma_n : s_k = b_0 \dots s_{k+l} = b_l \}$

where  $b = b_0 \dots b_l$

• A is transition matrix (no zero rows or zero columns)

• SSFT (two sided) A is  $(n \times n)$  transition matrix

$$\Sigma_A = \{ \Sigma \in \Sigma_n : A_{s_i, s_{i+1}} = 1 \forall i \in \mathbb{Z} \}$$



Now  $\Sigma_A \Leftrightarrow$  all bi-infinite allowable paths

•  $\Sigma_A$  is compact and completely invariant  $\nabla (\Sigma_A) = \Sigma_A$

matrix

Theorem: A is a transition matrix  $\Leftrightarrow$  A is irreducible

- $(\Sigma_A, \nabla)$  is transitive  $\Leftrightarrow$  A is primitive
- $(\Sigma_A, \nabla)$  is top. mixing  $\Leftrightarrow$  A is a single
- If A is irreducible  $\Rightarrow$  either  $\Sigma_A$  is a perfect set or it is a perfect set

geometric

• Smale's Horseshoe is an example that has been central to modern dynamics.

•  $F: S^2 \rightarrow S^2$  (2-sphere) whose recurrent set (closed recurrent points)

consists of 3 pieces

### Cantor Set

- $P^-$  a repelling fixed pt
- $\Lambda$  a compact, "hyperbolic" set conjugate to  $(\Sigma_2, \sigma)$
- $P^+$  an attracting fixed pts

$$\alpha(x) = P^-, \omega(x) = P^+$$

for  $x \in \Lambda$

and  $\Lambda$  is  $F$  invariant and

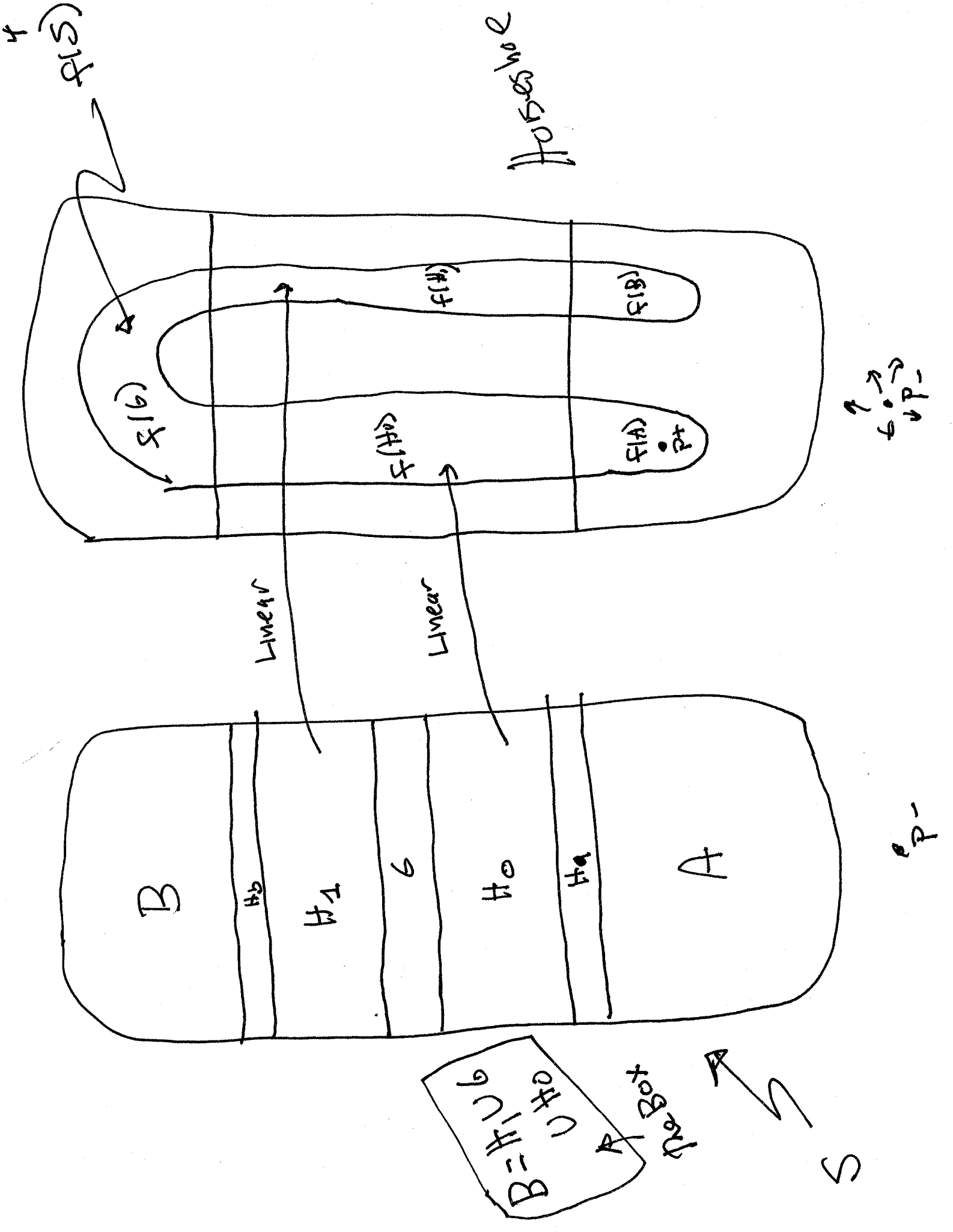
$F|_{\Lambda}$  is transitive, and so

$F|_{\Lambda}$

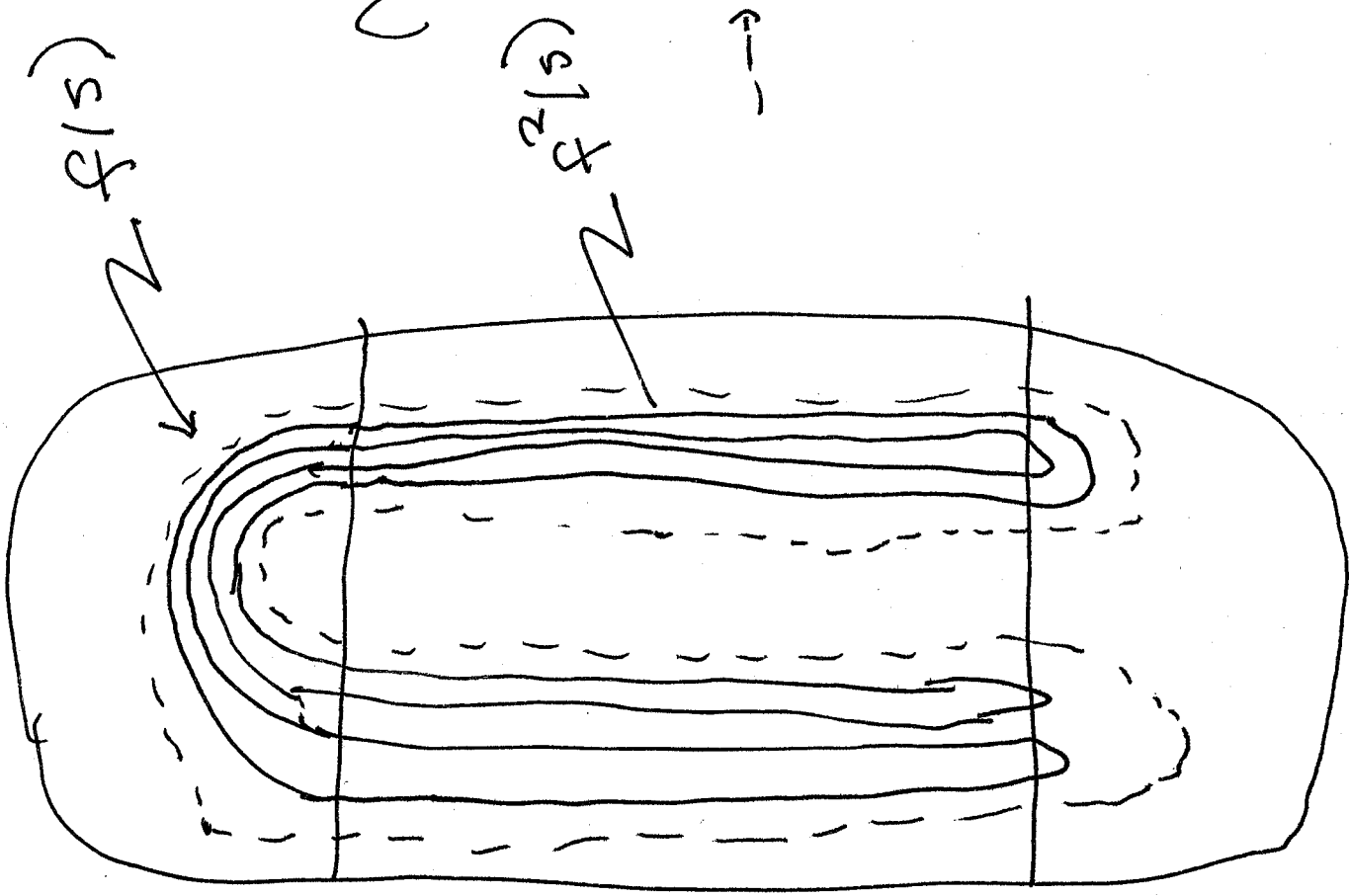
is dynamically irreducible

• We just sketch the details - See Devaney, "Intro to Chaotic Dynamics", Robinson "Stability, Symbolic Dynamics and Chaos"

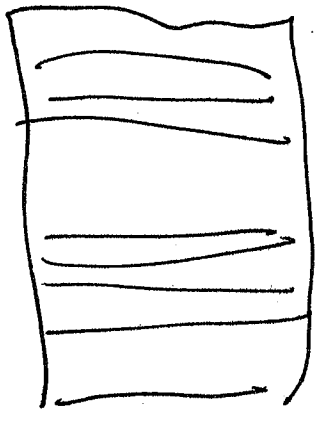
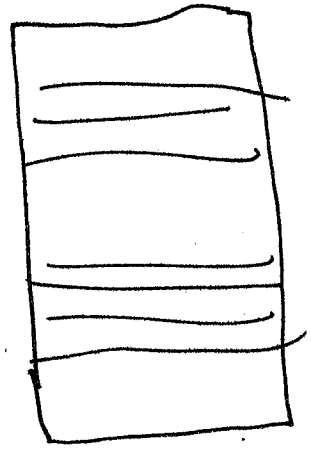
"Intro to Chaotic Dynamics"



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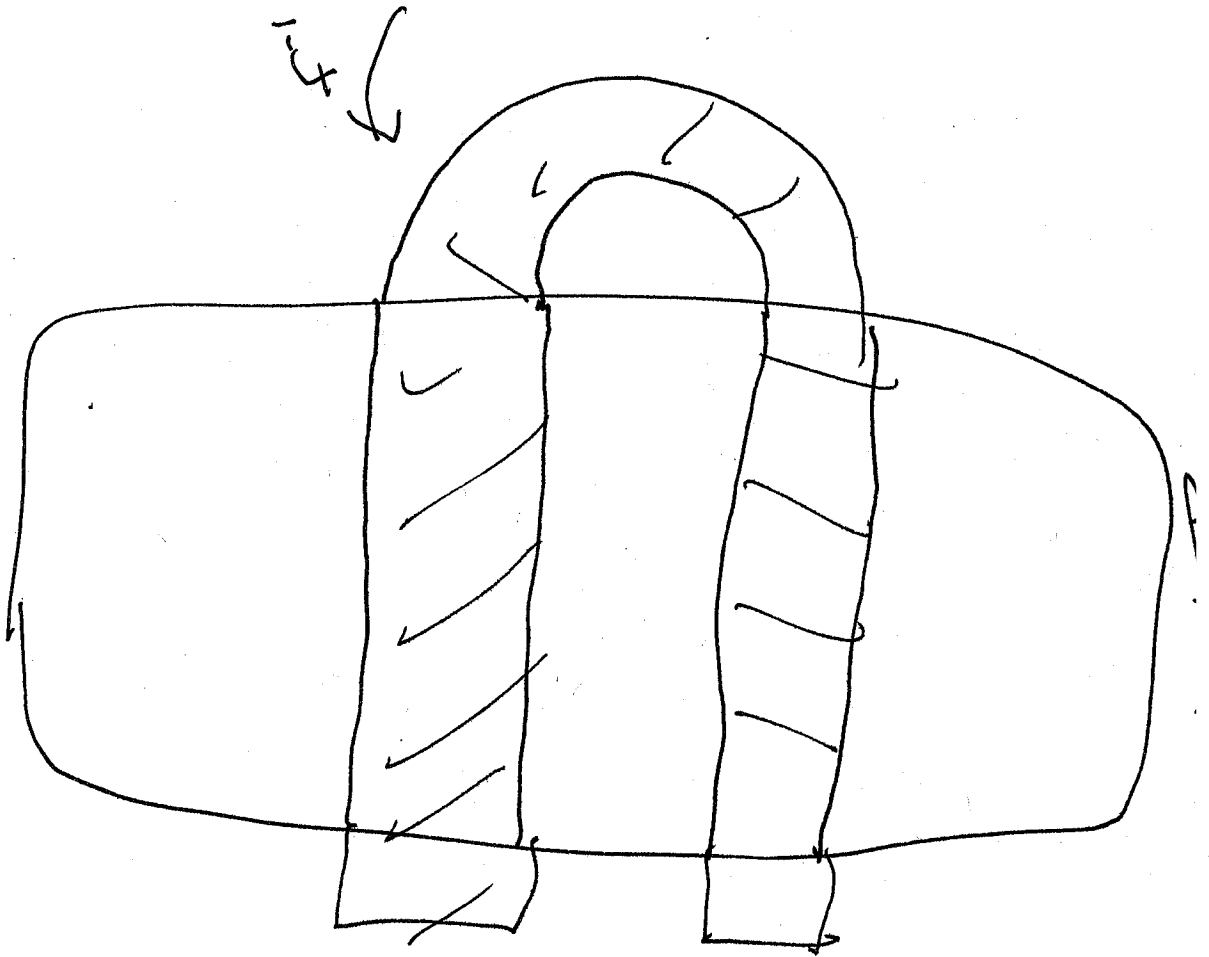
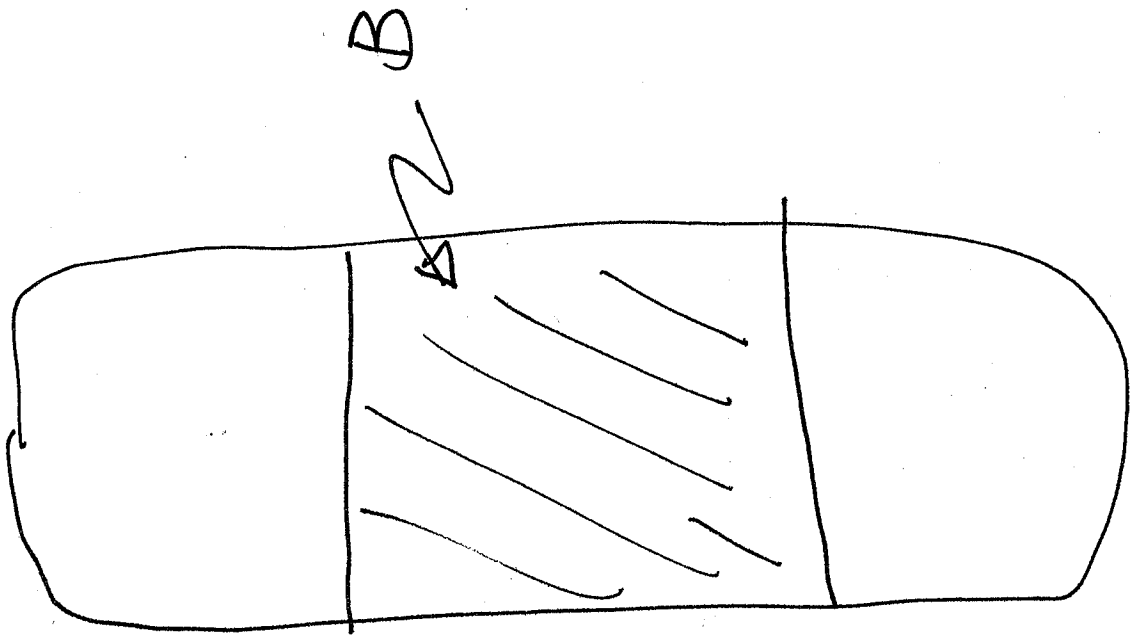


in  $\rightarrow$   
 $f_n(B)$   
 $H_0$



Each Cantor set  $\times$   
 interval

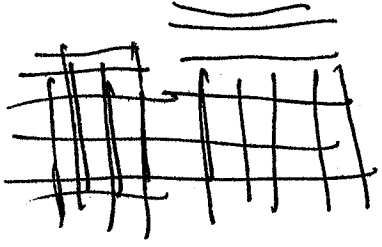
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$I_n$   $H_0 \cup H_1$   $\bigcup_{n \in \mathbb{N}} F_n(B)$  = Cantor set  $\times I_n$



$$\bigcap_{k \in \mathbb{Z}} F_n(B) = \text{Cantor set}$$



$$\{ \sum_{k \in \mathbb{N}} \frac{1}{3^k} \cdot x_k \mid x_k \in B \}$$

Play video

Use  $H_0$  and  $H_1$  as an address system  
for  $\mathbb{A}$

$$L: \mathbb{A} \rightarrow \Sigma_2 \quad (L(x))_k = S_k \Leftrightarrow f^k(x) \in H_{S_k}$$

usual itinerary code

is a topological

Theorem:  $L: \mathbb{A} \rightarrow \Sigma_2$

conjugacy.

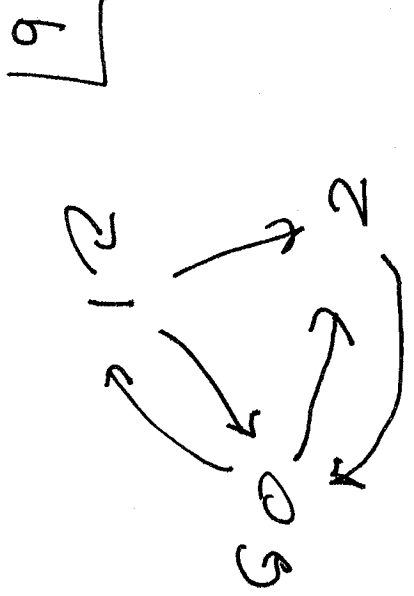
Much more to be said  $\neq$  or  $\mathbb{A}$

- hypersolic
- stable and unstable sets
- $\Sigma_2 \times \Sigma_2$  as  $n \rightarrow \infty$

$$W^s(x) = \Sigma_2 \times \Sigma_2 \Rightarrow y \text{ as } n \rightarrow \infty$$

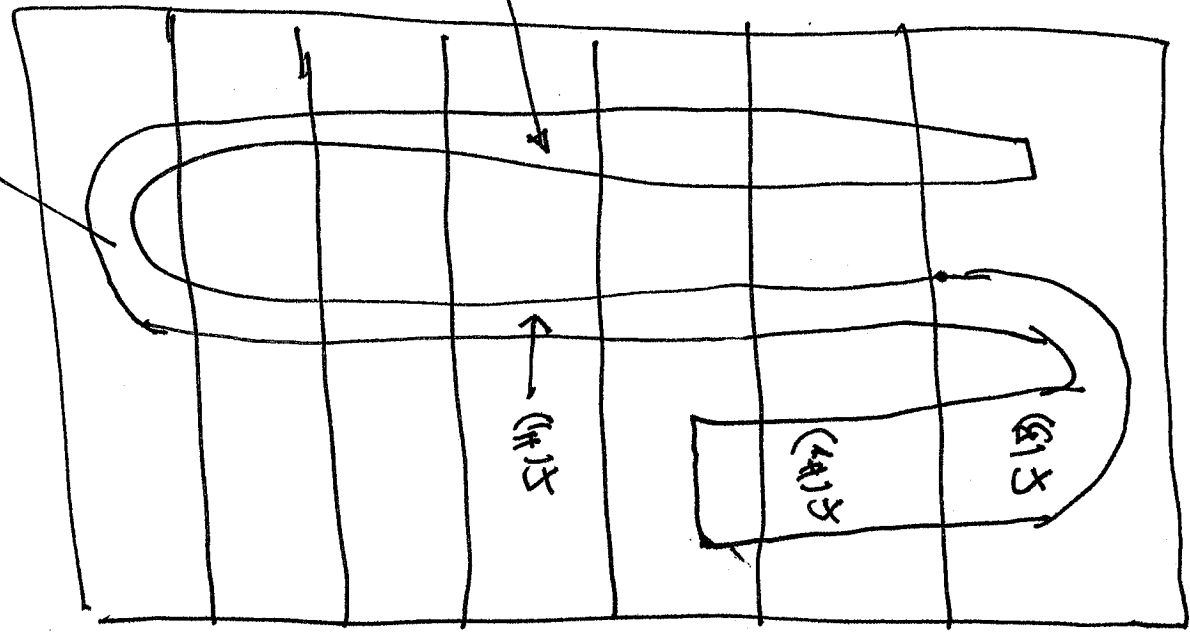


Other examples



$\lambda$  is all points that stay in  $H_0 \cup H_1 \cup H_2$  for all forward and backward iterates

$H_2$   
 $B$   
 $H_1$   
 $A$   
 $H_0$



$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$(-1, f|_A)$  top conjugate  
 $\rightarrow (\Sigma A, \tau)$   
 top mixing  $\Rightarrow$  transitive  
 $A^2 > 0$  so primitive

This lecture included these two youtube videos made by Prof. R. Ghrist at the University of Pennsylvania

<https://www.youtube.com/watch?v=SrJm6bkLuPs>

<https://www.youtube.com/watch?v=skvCUST4LPk>