

$$(1) \quad Df(x_1, x_2) = \begin{bmatrix} 2x_1x_2 & x_1^2 \\ x_2^3 & 3x_1x_2^2 \\ x_2 & x_1 \end{bmatrix}$$

$$Dg(y_1, y_2, y_3) = \begin{bmatrix} y_2 & y_1 & 0 \\ 0 & y_3 & y_2 \end{bmatrix}$$

$$Dg \circ f(x_1, x_2) = \begin{bmatrix} x_1x_2^3 & x_1^2x_2 & 0 \\ 0 & x_1x_2 & x_1x_2^3 \end{bmatrix}$$

$$Dh(x_1, x_2) = Dg \circ f(x_1, x_2) \cdot Df(x_1, x_2)$$

$$= \begin{bmatrix} x_1x_2^3 & x_1^2x_2 & 0 \\ 0 & x_1x_2 & x_1x_2^3 \end{bmatrix} \begin{bmatrix} 2x_1x_2 & x_1^2 \\ x_2^3 & 3x_1x_2^2 \\ x_2 & x_1 \end{bmatrix}$$

$$= \begin{bmatrix} 2x_1^2 x_2^4 + x_1^2 x_2^4 \\ x_1 x_2^4 + x_1 x_2^4 \end{bmatrix}$$

$$\left. \begin{aligned} x_1^3 x_2^3 + 3x_1^3 x_2^3 \\ 3x_1^2 x_2^3 + x_1^2 x_2^3 \end{aligned} \right\}$$

$$\Rightarrow \begin{bmatrix} 3x_1^2 x_2^4 \\ 2x_1 x_2^4 \end{bmatrix}$$

$$\left. \begin{aligned} 4x_1^3 x_2^3 \\ 4x_1^2 x_2^3 \end{aligned} \right\}$$

(2) It is simplest to use the formula for the DFT

$$\hat{X}_j = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} X_k \omega^{-kj} = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} \omega^{-kj}$$

$$= \frac{1}{\sqrt{N}} (1 + \omega^{-j} + \omega^{-2j} + \dots + \omega^{-(N-1)j})$$

$$= \frac{1}{\sqrt{N}} \cdot 0 \quad \text{when } j \neq 0$$

$$= \frac{1}{\sqrt{N}} \cdot N \quad \text{when } j = 0$$

using
 $(1-z)(1+z+\dots+z^{N-1}) = 1-z^N$
 and
 $\omega^{jN} = 1$

So DFT(One) = $\begin{bmatrix} \sqrt{N} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$

(3) For hand calculations it is usually easier to find the matrix M

$$u * v = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} * \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 2 \\ 2 & 1 & 3 \\ 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}$$

$$= \begin{bmatrix} 6 \\ -1 \\ 10 \end{bmatrix}$$

(4) $w_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ $w_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ given basis

(9) $\|w_1\|^2 = \langle w_1, w_1 \rangle = [1 \ 0] \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = [2 \ 1] \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 2$

so $z_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix}$

$$v_2 = w_2 - \langle w_2, z_1 \rangle z_1$$
$$= \begin{bmatrix} 0 \\ 1 \end{bmatrix} - \left([0 \ 1] \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix} \right) \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 1 \end{bmatrix} - [1 \ 1] \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{2}} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$$

check $\langle v_2, z_1 \rangle = [-1/2 \ 1] \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix}$

$$= [0 \ 1/2] \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix} = 0 \quad \checkmark$$

(4) cont

$$z_2 = \frac{v_2}{\|v_2\|}$$

$$\|v_2\|^2 = \langle v_2, v_2 \rangle = \begin{bmatrix} -\frac{1}{2} & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1/2 \end{bmatrix} \begin{bmatrix} -1/2 \\ 1 \end{bmatrix} = 1/2$$

$$\text{so } z_2 = \frac{\begin{bmatrix} -1/2 \\ 1 \end{bmatrix}}{\frac{1}{\sqrt{2}}} = \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2} \end{bmatrix}$$

$$\text{check } \langle z_2, z_2 \rangle = \begin{bmatrix} -\frac{\sqrt{2}}{2} & \sqrt{2} \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & \sqrt{2} - \frac{\sqrt{2}}{2} \end{bmatrix} \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2} \end{bmatrix}$$

$$= 0 + 2 - \frac{2}{2} = 1 \quad \checkmark$$

$$4(b) \quad \vec{v} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \alpha_1 \vec{q}_1 + \alpha_2 \vec{q}_2$$

$$\alpha_1 = \langle \vec{v}, \vec{q}_1 \rangle = \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix} = -1/\sqrt{2}$$

$$\alpha_2 = \langle \vec{v}, \vec{q}_2 \rangle = \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2} \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 \end{bmatrix} \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2} \end{bmatrix}$$

$$= \sqrt{2}/2$$

$$\text{So } \begin{bmatrix} -1 \\ 1 \end{bmatrix} = -1/\sqrt{2} \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix} + \sqrt{2}/2 \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2} \end{bmatrix}$$

$$\begin{array}{l} \uparrow \\ \text{check} \end{array} \begin{bmatrix} -1/2 \\ 0 \end{bmatrix} + \begin{bmatrix} -1/2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \quad \checkmark$$

(5)

$$g = \begin{bmatrix} -1/2 \\ 1/2 \\ 0 \\ 0 \\ 1/2 \end{bmatrix}$$

$$M = \begin{bmatrix} -1/2 & 1/2 & 0 & 0 & 1/2 \\ 1/2 & -1/2 & 1/2 & 0 & 0 \\ 0 & 1/2 & -1/2 & 1/2 & 1/2 \\ 0 & 0 & 1/2 & -1/2 & 0 \\ 1/2 & 0 & 0 & 1/2 & -1/2 \end{bmatrix}$$

(6) (A) (a)

$$F(x, y) = \left[\sigma(\omega_{11}x_1 + \omega_{21}x_2 + b_1), \sigma(\omega_{12}x_1 + \omega_{22}x_2 + b_2) \right]^T$$

$$(b) F(x, y) = \delta_1 \sigma(\omega_1 x_1 + b_1) + \delta_2 \sigma(\omega_2 x_1 + b_2) + \delta_3 \sigma(\omega_3 x_1 + b_3)$$

$$(c) F(x, y) = \sigma(\omega_1 x_1 + \omega_2 x_2 + b)$$

(B) (a) Let $z_1 = \omega_{11}x_1 + \omega_{21}x_2 + b_1$, $z_2 = \omega_{12}x_1 + \omega_{22}x_2 + b_2$
 $m = \omega$'s then b's.

$$DF(x, y) = \begin{bmatrix} \sigma'(z_1)x_1 & \sigma'(z_1)x_2 & 0 & 0 & \sigma'(z_1) & 0 \\ 0 & 0 & \sigma'(z_2)x_1 & \sigma'(z_2)x_2 & 0 & \sigma'(z_2) \end{bmatrix}$$

(b) $m = \omega$'s then b's then δ 's then B

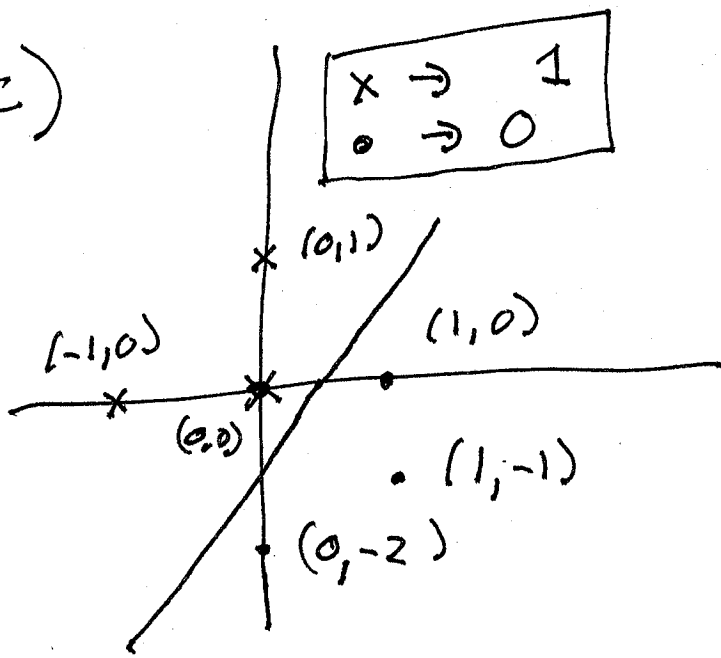
$$DF = \left[\delta_1 \sigma'(z_1)x_1 \quad \delta_2 \sigma'(z_2)x_1 \quad \delta_3 \sigma'(z_3)x_1 \rightarrow \right.$$

$$\rightarrow \delta_1 \sigma'(z_1) \quad \delta_2 \sigma'(z_2) \quad \delta_3 \sigma'(z_3) \rightarrow$$

$$\rightarrow \sigma(z_1) \quad \sigma(z_2) \quad \sigma(z_3) \quad \mathbf{1} \left. \right]$$

as single 1×10 vector

6 (c)



one decision line passes through $(0, -1)$ and $(\frac{1}{2}, 0)$
 OR $2x_1 - x_2 - 1 = 0$
 putting in $(0, 0)$ yields -1 and $\nabla_S(-1) = 0$

so we switch the signs
 $w_1 = -2, w_2 = 1, b = 1$ or

$$F(x, \sigma) = \nabla_S(-2x_1 + x_2 + 1)$$

$$(D) \left[\nabla_R(2 \cdot 1 + 3(-1) + 3), \nabla_R(1 \cdot 1 + 2(-1) + 0) \right]$$

$$= \begin{bmatrix} \nabla_R(2) \\ \nabla_R(-1) \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$