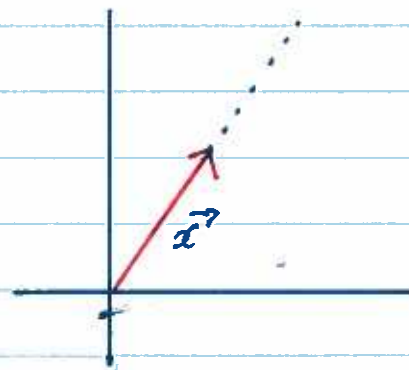
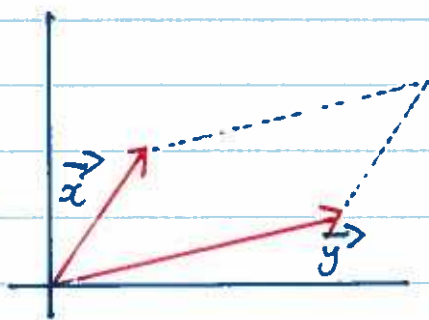


Chapter 1 Vector Spaces

1.1 Introduction

Addition & Scalar Multiplication of Vector in The Plane



Properties

1. For all vectors \vec{x}, \vec{y} , $\vec{x} + \vec{y} =$
2. For all vectors $\vec{x}, \vec{y}, \vec{z}$, $(\vec{x} + \vec{y}) + \vec{z} =$
3. There exists a vector $\vec{0}$ such that
4. For each vector \vec{x} there is a vector \vec{y} such that
5. For each vector \vec{x} , $1\vec{x} =$
6. For any real numbers a, b and any vector \vec{x}
 $(ab)\vec{x} =$
7. For any real number a and any vectors \vec{x}, \vec{y} ,
 $a(\vec{x} + \vec{y}) =$
8. For any real numbers a, b and any vector \vec{x}
 $(a + b)\vec{x} =$

1.2 Vector Spaces

Definition A vector space V over a field F is a set V (of mathematical objects) with two operations (_____ and _____) defined so that for each pair \vec{u}, \vec{v} in V there is a _____ element _____ in _____ and for each _____ and each _____ there is a unique element _____ such that the following conditions hold:

(VS1) For all \vec{u}, \vec{v} in V , $\vec{u} + \vec{v} =$ _____.

(VS2) For all $\vec{u}, \vec{v}, \vec{w}$ in V , $\vec{u} + (\vec{v} + \vec{w}) =$ _____.

(VS3) There exists an element _____ in V such that $\vec{u} +$ _____ $= \vec{u}$ for _____.

(VS4) For each _____ there exists _____ such that _____ $= \vec{0}$.

(VS5) For each $\vec{u} \in V$, $1 \vec{u} =$ _____.

(VS6) For all $a, b \in$ _____ and $\vec{u} \in V$,
(ab) $\vec{u} =$ _____.

(VS7) For all $a \in$ _____ and $\vec{u}, \vec{v} \in V$,
 $a(\vec{u} + \vec{v}) =$ _____.

(VS8) For all $a, b \in \dots$ and \dots
 $(a+b)\vec{u} = \dots$

NOTE

- (1) The definition of a field is given in \dots .
- (2) In our course F is usually \dots or \dots .
- (3) The elements of F are called \dots .
 The elements of V are called \dots .
- (4) [PROOF LATER] The vector \vec{v} in (VS4) is \dots
 and is denoted by \dots .
- (5) [PROOF LATER] The vector $\vec{0}$ is \dots .

Examples of Vector Spaces

- (1) Let F be a field and n be a positive integer.
 Define
 $F^n := \dots$

Let $\vec{x} = \dots$, $\vec{y} = \dots \in F^n$ & $a \in F$.
 Define

$$\vec{x} + \vec{y} := \dots, \quad a\vec{x} = \dots$$

Then with these operations F^n is a \dots
 over \dots .

Example \mathbb{R} is a _____.

$$\mathbb{R}^4 =$$

is a _____ over _____.

(2) Let F be a field.

Let $P(F) =$ _____

Then $P(F)$ is a vector space over _____ with addition and scalar multiplication defined in the usual way.

Example Let

$$p_1(x) =$$

$$p_2(x) =$$

\in

$$\text{Then } p_1(x) + p_2(x) =$$

$$3 p_1(x) =$$

Theorem (Cancellation Law for Vector Addition).

Let V be a vector space over a field F .

If $\vec{u}, \vec{v}, \vec{w} \in V$ and

$$\vec{u} + \vec{w} =$$

then $\vec{u} =$ _____.

Proof: Suppose $\vec{u}, \vec{v}, \vec{w} \in V$ and
 (*) $\vec{u} + \vec{w} = \vec{v} + \vec{w}$. Then

$$\begin{aligned} \vec{u} &= \vec{u} + \vec{0} && \text{(by ---)} \\ &= \text{---} && \text{(by --- for ---)} \\ &= \text{---} && \text{(by ---)} \\ &= \text{---} && \text{(by (*))} \\ &= \text{---} && \text{(by ---)} \\ &= \text{---} && \text{(---)} \\ &= \text{---} && \text{(by ---)}. \end{aligned}$$

Thus $\vec{u} = \text{---}$. □

Corollary 1 The vector $\vec{0}$ in (VS3) is ---.

Proof We know that

(A) $\vec{u} + \vec{0} = \text{---}$ for ---.

Suppose $\vec{z} \in V$ and

(B) --- = --- for ---.

We will show --- = ---.

By (A), $\vec{0} + \vec{0} = \underline{\hspace{2cm}}$.

By (B) $\vec{0} + \vec{z} = \underline{\hspace{2cm}}$.

Hence

$\vec{0} + \vec{0} = \underline{\hspace{2cm}},$

and

$\vec{0} + \vec{0} = \underline{\hspace{2cm}}$ (by $\underline{\hspace{2cm}}$)

Hence $\vec{0} = \underline{\hspace{2cm}}$ by Cancellation Law.

Thus the vector $\underline{\hspace{2cm}}$ \square

Corollary 2 The vector \vec{v} in (VS 4) is $\underline{\hspace{2cm}}$.

Proof. Suppose V is a vector space over F , $\vec{u} \in V$ and

$\vec{u} + \vec{v}_1 = \underline{\hspace{2cm}}$

$\vec{u} + \vec{v}_2 = \underline{\hspace{2cm}}$

for $\underline{\hspace{2cm}}$

We will show $\underline{\hspace{2cm}} = \underline{\hspace{2cm}}$.

Then

$\vec{v}_1 + \vec{u} = \underline{\hspace{2cm}} = \underline{\hspace{2cm}},$

$\vec{v}_2 + \vec{u} = \underline{\hspace{2cm}} = \underline{\hspace{2cm}}.$

Thus

$\vec{v}_1 + \vec{u} = \underline{\hspace{2cm}}$ and

$\vec{v}_1 = \underline{\hspace{2cm}}$

by the $\underline{\hspace{2cm}}$ Therefore the vector \vec{v} in (VS 4) is $\underline{\hspace{2cm}} \square$

More Examples

(3) Let m, n be positive integers and F be a field.
An $m \times n$ matrix with entries from F has the form

$$A = \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \end{pmatrix} \leftarrow \text{ith row}$$

↑
j-th column

where each $\dots \in \dots$

The set of such matrices is denoted by $M_{m \times n}(F)$.

Let $A, B \in M_{m \times n}(F)$ and $c \in F$.

Let $(A)_{ij}$ denote the entry in the i -th row and j -th column of A .

We define $A+B$ and cA by

$$(A+B)_{ij} = A_{ij} + B_{ij}$$

$$(cA)_{ij} = cA_{ij}$$

for $1 \leq i \leq m$ and $1 \leq j \leq n$.

Then $M_{m \times n}(F)$ is a vector space over F .

Example

$$M_{3 \times 2}(\mathbb{R}) = \left\{ \right.$$

Let $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}$, $B = \begin{pmatrix} 2 & -1 \\ -5 & -6 \\ 0 & 7 \end{pmatrix}$.

Then

$A + B =$, $2A =$

(*) Let S be a nonempty & F be a field.

Let

$\mathcal{F}(S, F)$ be the set _____

[For example if $S = \{x \in \mathbb{R} : x > 0\}$, $F = \mathbb{R}$

$f(x) =$, $g(x) =$ (for $x \in$ ---).
Then

$f, g \in \mathcal{F}(S, F) =$ _____].

For $f, g \in \mathcal{F}(S, F)$ define $f + g$ by

$(f + g)(x) :=$

and cf by (where $c \in$) by

$(cf)(x) :=$

Under these operations $\mathcal{F}(S, F)$ is a _____.

NOTE:

(1) $P(F) \subset$ _____.

(2) The zero vector in $\mathcal{F}(S, F)$ is the _____ function $z(x) =$ _____ for _____.

Theorem Let V be a vector space over a field F .

(1) If $\vec{u} \in V$ then $0\vec{u} =$ _____.

(2) If $\vec{u} \in V$ and $a \in F$ then $(-a)\vec{u} = -(\text{_____}) = a(\text{_____})$.

(3) If $a \in F$ then $a\vec{0} =$ _____.

PROOF Suppose V is a vector space over a field F .

(1) Suppose $\vec{u} \in V$. Since F is a field we know

$$0\vec{u} + 0\vec{u} = \text{_____} \quad (\text{by } \text{_____})$$

$$= \text{_____} \quad (\text{since } \text{_____})$$

$$= \text{_____} \quad (\text{by } \text{_____})$$

Thus

$$0\vec{u} + 0\vec{u} = \text{_____},$$

and

$$0\vec{u} = \text{_____}$$

by the _____

□

(2) Let $\vec{u} \in V$, $a \in F$.
 $a\vec{u} + (-a)\vec{u} =$

$=$

$=$

Hence $(-a)\vec{u} =$

by

Letting $a=1$ we have

(*) $(-1)\vec{u} =$

(by ---)

for any ---.

So

$-(a\vec{u}) =$

$=$

$=$

since in a field $(-1)a =$

(3) Let $a \in F$. Then

$$\text{Thus } \vec{0} + \vec{0} = \quad (\text{by } \quad)$$

$$a(\vec{0} + \vec{0}) =$$

But

$$a(\vec{0} + \vec{0}) = \quad (\text{by } \quad)$$

Hence

$$a\vec{0} + a\vec{0} =$$

=

(by)

Thus

$$a\vec{0} + a\vec{0} =$$

and

$$a\vec{0} =$$

by the ----- \square

Example

Let $S = \{ (a_1, a_2) : a_1, a_2 \in \mathbb{R} \}$.

For $(a_1, a_2), (b_1, b_2) \in S$ & $c \in \mathbb{R}$ define

$$(a_1, a_2) + (b_1, b_2) := (a_1 + b_1, a_2 - b_2),$$

$$c(a_1, a_2) := (ca_1, ca_2).$$

Show that S is not a vector space over \mathbb{R} .

1.3 Subspaces

Definition Let V be a vector space over a field F .

W of V is a subspace of V
if

Theorem 1.3 Let V be a vector space over field F and
suppose $W \subseteq V$.

W is a subspace of V if and only if the following
3 conditions hold:

- (1)
- (2)
- (3)

PROOF:

(\Rightarrow) Suppose W is a subspace of V .

Then $W \subseteq V$ and W is a vector space.

So W must contain a zero vector $\vec{0} \in W \subseteq V$.

(\Leftarrow) Suppose V is a vector space over a field F , $W \subset V$ and (1), (2), (3) hold.

Then addition & scalar multiplication are

axioms (VS1), (VS2), (VS3), (VS4), (VS7), (VS8) hold in W

since and they hold in V

axiom (VS3) holds in W by

axiom (VS4) holds in W since

all axioms hold in W so that

Example

Show that $S = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 : x_1 + x_2 + x_3 = 0 \right\}$ is a subspace of \mathbb{R}^3 .

Clearly also $\vec{0} =$

Suppose $\vec{x} = \begin{bmatrix} \\ \\ \end{bmatrix}, \vec{y} = \begin{bmatrix} \\ \\ \end{bmatrix} \in$

The Transpose of a Matrix

The transpose of a matrix A is obtained by _____ and is denoted by _____.

Example Let $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$

Then $A^t =$

NOTE: If A is $m \times n$ then A^t is _____ and

$$(A^t)_{ij} =$$

Ex Let $A, B \in M_{\text{max}}(F)$, $a, b \in F$.

Prove that

$$(aA + bB)^t = aA^t + bB^t.$$

PROOF

$$\left((aA + bB)^t \right)_{ij} =$$

Definition A matrix A is symmetric if _____.

NOTE Symmetric matrices are square since $A^t = A$
implies _____.

Example $A = \begin{pmatrix} 1 & 2 & 3 \\ & 4 & 5 \\ & & 6 \end{pmatrix}$

is symmetric since _____.

Ex Let $W = \{ A \in M_{n \times n}(F) : A = A^t \}$.

Prove that W is a subspace of _____.

PROOF:

Clearly

The zero

Suppose $A, B \in ______ and $c \in ______$$

Ex. Let $W = \{ p(x) \in P(F) : p(x) = x^2 g(x) \text{ for some } g(x) \in P(F) \}$.

Show that W is a subspace of _____.

Clearly

The zero

Let $p_1(x), p_2(x) \in \dots$ and $c \in \dots$

Example

Let $W = \left\{ \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \in M_{3 \times 3}(\mathbb{R}) : a_{11} + a_{22} + a_{33} = 1 \right\}$

Determine whether W is a subspace of $M_{3 \times 3}(\mathbb{R})$.

Example

$$\text{Let } W = \left\{ A \in M_{3 \times 3}(\mathbb{R}) : A_{11} + A_{22} + A_{33} = 0 \right\}.$$

Determine whether W is a subspace of $M_{3 \times 3}(\mathbb{R})$ and prove it.

Theorem Let V_1, V_2 be subspaces of vector space V over F . Then $V_1 \cap V_2$ is a subspace of V .

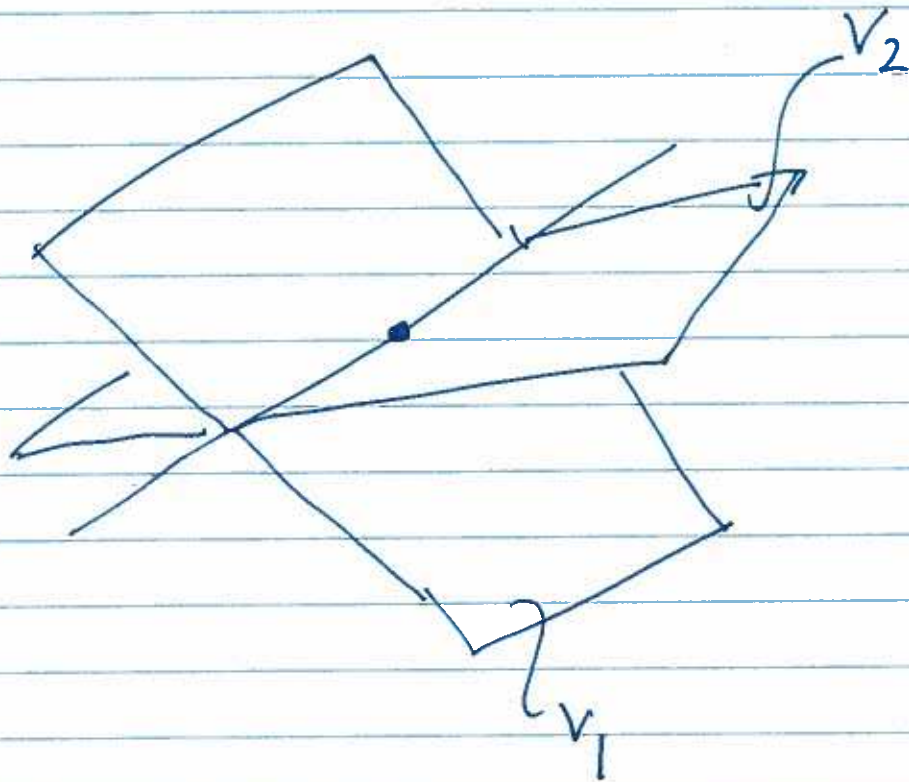
Proof:

Suppose V_1, V_2 are subspaces of vector space V over F .

Then V_1, V_2 are subspaces of V .

Let $\vec{0}$ be the zero vector of V .

Suppose $\vec{u}, \vec{v} \in V_1 \cap V_2$ and $c \in F$.



An example
in
 \mathbb{R}^3

Ex Is $V_1 \cup V_2$ a subspace of V if
 V_1, V_2 are subspaces of V ?

Theorem Suppose I is a set & V_α is a subspace
of a vector space V over F for each $\alpha \in I$.

Then

$$W =$$

is a subspace of -----.

NOTE $\vec{w} \in W$ iff

Definition

Let S_1, S_2 be non-empty subset of a vector space V .

For

$$S_1 + S_2 := \left\{ \quad \quad \quad \right\}$$

Example Let $S_1 = \left\{ \begin{bmatrix} a \\ a \\ -2a \end{bmatrix} : a \in \mathbb{R} \right\}$,

$S_2 = \left\{ \begin{bmatrix} b \\ 0 \\ b \end{bmatrix} : b \in \mathbb{R} \right\}$. Determine whether $\vec{u} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \in S_1 + S_2$?

Definition Let W_1, W_2 be subspaces of a vector space V over F .

V is the direct sum of W_1 and W_2 if

- (1)
- (2)

Note. In this case we write -----.

Example

$$\text{Let } W_1 = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x + y + z = 0 \right\},$$

$$W_2 = \left\{ \begin{bmatrix} a \\ a \\ a \end{bmatrix} : a \in \mathbb{R} \right\}.$$

Show that $\mathbb{R}^3 = W_1 \oplus W_2$.

Theorem (Ex 23, p.22)

Let W_1, W_2 be subspaces of a vector space V over F .

Then

- (i) $W_1 + W_2$ is a _____ that _____.
- (ii) If W is a subspace of V that contains both W_1 and W_2 then _____.

Theorem (Ex 30, p.23)

Let W_1, W_2 be subspaces of a vector space V over F .

Then

$$V = W_1 \oplus W_2$$

if and only if every vector $\vec{v} \in V$ can be written
as

$$\vec{v} = \underline{\quad} + \underline{\quad}$$

where _____.

1.4 Linear Equations and Systems of Linear Equations

Definition Let S be a non-empty subset of a vector space V (over F). We say $\vec{v} \in V$ is a linear combination of vectors in S if

----- and -----
 ----- such that
 ----- = -----

In this case, we say \vec{v} is a -----
 ----- and
 are \mathbb{R} -----

Example Determine whether the vector $\vec{v} = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \in \mathbb{R}^3$ is a linear combination of $\vec{v}_1 = \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 6 \\ 7 \\ 2 \end{bmatrix}$.

Example Determine whether the vector $\vec{v} = \begin{bmatrix} 7 \\ 9 \\ 1 \end{bmatrix} \in \mathbb{R}^3$ is a linear combination of $\vec{v}_1 = \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 6 \\ 7 \\ 2 \end{bmatrix}$.

Example Determine whether the polynomial

$$p(x) = 5x^3 + x^2 + 3x - 5$$

is a linear combination of

$$p_1(x) = x^3 + 2x^2 + 3x - 4,$$

$$p_2(x) = x^3 - x^2 - x + 1.$$

(p.28)

Definition:

a linear system of m equations in the n unknowns x_1, x_2, \dots, x_n (over a field F) has the form

$$(*) \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

where each $a_{ij}, b_j \in \dots$ and each variable $x_j \in \dots$.

(*) corresponds to the augmented matrix

$$\left(\begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{array} \right)$$

Operations that preserve the solution set for a linear system over F are

- (1) Interchange two \dots (\dots)
- (2) Multiply an equation by a \dots (\dots)
- (3) Add a multiple of a_i \dots (\dots)

THESE CORRESPOND TO OPERATIONS ON THE CORRESPONDING AUGMENTED MATRIX:

- (1)
- (2)
- (3)

Linear system is in reduced Echelon form if

- (1) The first nonzero coefficient in each equation is _____.
- (2) If an unknown is the first unknown with a _____ coefficient in _____ equation, then that unknown occurs with a _____ in each of _____
_____ the first such unknown in an equation is called _____ variable.
- (3) The leading variable of each equation has a _____ subscript than leading variable of _____ equations.

The process of obtaining Reduced Echelon Form is called _____ Elimination.

NOTE: If we obtain an equation of the form $0=c$ where $c \neq 0$, the system is called _____ and has _____ solutions.

Definition: Let V be a vector space over F and suppose $\emptyset \neq S \subset V$. The span of S denoted by _____ is defined by

$$\text{Span}(S) = \left\{ \vec{v} : \text{-----} \right\}$$

By convention we define $\text{Span}(\emptyset) = \text{-----}$.

Example Let $\vec{v}_1 = \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 6 \\ 7 \\ 2 \end{bmatrix} \in \mathbb{R}^3$.

(i) Is $\begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \in \text{Span}(\{\vec{v}_1, \vec{v}_2\})$?

(ii) Is $\begin{bmatrix} 7 \\ 9 \\ 1 \end{bmatrix} \in \text{Span}(\{\vec{v}_1, \vec{v}_2\})$?

Example In the vector space $P(\mathbb{R})$ let

$$p(x) = 5x^3 + x^2 + 3x - 5,$$

$$p_1(x) = x^3 + 2x^2 + 3x - 4,$$

$$p_2(x) = x^3 - x^2 - x + 1,$$

$$S = \{p_1(x), p_2(x)\}.$$

Determine whether $p(x)$ is in the span of S .

Theorem 1.5

Let V be a vector space over F and suppose $S \subset V$.
 Then

(1) $\text{Span}(S)$ is a _____ of V .

(2) If W is a subspace of V and $S \subset W$
 then $\text{Span}(S)$ _____.

PROOF:

(1) Case 1 $S = \emptyset$.

Case 2. $S \neq \emptyset$.

(2) Now suppose $W \subset V$ and W is a subspace of V , ^(p37)

Definition Let $S \subset V$ where V is a vector space.
We say S spans V (or -----) V if

NOTE

(1) $S \subset V$ so $\text{Span}(S)$ -----

Hence $\text{Span}(S) = V$ iff -----;

ie iff each vector of -----

(2) In this case (see defn) we say vectors in S

Example Show that the vectors

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 1 \\ 0 \\ -4 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad \text{in } \mathbb{R}^3$$

generated \mathbb{R}^3 .

Example Show that $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $B = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, $C = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

generate the vector space

$$V = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M_{2 \times 2}(\mathbb{R}) : a+d=0 \right\}$$

Definition Two linear systems are equivalent if _____.

We notation \Leftrightarrow to mean _____;
ie have _____.

Example Solve the linear system

$$\begin{cases} 3x_2 - 6x_3 + 6x_4 + 4x_5 = -5 \\ 3x_1 - 7x_2 + 8x_3 - 5x_4 + 8x_5 = 9 \\ 3x_1 - 9x_2 + 12x_3 - 9x_4 + 6x_5 = 15 \end{cases} \left(\begin{array}{ccccc|c} 0 & 3 & 6 & 6 & 4 & -5 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 3 & -9 & 12 & -9 & 6 & 15 \end{array} \right)$$

$\frac{1}{3}R_3$

$$\Leftrightarrow \begin{cases} 3x_2 - 6x_3 + 6x_4 + 4x_5 = -5 \\ 3x_1 - 7x_2 + 8x_3 - 5x_4 + 8x_5 = 9 \\ x_1 - 3x_2 + 4x_3 - 3x_4 + 2x_5 = 5 \end{cases} \left(\begin{array}{ccccc|c} & & & & & \\ & & & & & \\ & & & & & \end{array} \right)$$

$$\Leftrightarrow \begin{cases} x_1 - 3x_2 + 4x_3 - 3x_4 + 2x_5 = 5 \\ 3x_1 - 7x_2 + 8x_3 - 5x_4 + 8x_5 = 9 \\ 3x_2 - 6x_3 + 6x_4 + 4x_5 = -5 \end{cases} \left(\begin{array}{ccccc|c} 1 & -3 & 4 & -3 & 2 & 5 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{array} \right)$$

$$\Leftrightarrow \begin{cases} x_1 - 3x_2 + 4x_3 - 3x_4 + 2x_5 = 5 \\ 2x_2 - 4x_3 + 4x_4 + 2x_5 = 6 \\ 3x_2 - 6x_3 + 6x_4 + 4x_5 = -5 \end{cases} \left(\begin{array}{ccccc|c} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 2 & -4 & 4 & 2 & 6 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{array} \right)$$

$$\Leftrightarrow \begin{cases} x_1 - 3x_2 + 4x_3 - 3x_4 + 2x_5 = 5 \\ x_2 - 2x_3 + 2x_4 + x_5 = -3 \\ 3x_2 - 6x_3 + 6x_4 + 4x_5 = -5 \end{cases} \left(\begin{array}{ccccc|c} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{array} \right)$$

$$\Leftrightarrow \begin{cases} x_1 - 3x_2 + 4x_3 - 3x_4 + 2x_5 = 5 \\ x_2 - 2x_3 + 2x_4 + x_5 = -3 \\ x_5 = 4 \end{cases} \quad \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \end{array} \quad \begin{array}{c} (P.37) \\ \\ \end{array} \left(\begin{array}{ccccc|c} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{array} \right)$$

$$\Leftrightarrow \begin{cases} x_1 - 3x_2 + 4x_3 - 3x_4 = -3 \\ x_2 - 2x_3 + 2x_4 = -7 \\ x_5 = 4 \end{cases} \left(\begin{array}{ccccc|c} 1 & -3 & 4 & -3 & 0 & -3 \\ 0 & 1 & -2 & 2 & 0 & -7 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{array} \right)$$

$$\Leftrightarrow \begin{cases} x_1 - 2x_3 + 3x_4 = -24 \\ x_2 - 2x_3 + 2x_4 = -7 \\ x_5 = 4 \end{cases} \left(\begin{array}{ccccc|c} 1 & 0 & -2 & 3 & 0 & -24 \\ 0 & 1 & -2 & 2 & 0 & -7 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{array} \right)$$

$\Leftrightarrow \left\{ \right.$

where

The solution set

$S = \{$

1.5 Linear Dependence & Linear Independence (p. 38)

Definition: Let $S \subset V$ where V is a vector space over F .
 S is linearly dependent if

_____ in _____ and
_____ such that
(*) _____ = _____

Otherwise we say S is _____.

NOTE:

(1) If S is linearly dependent then S is _____.
The $\emptyset = \{ \}$ is _____.

(2) $S = \{ \vec{0} \}$ is _____
size _____.

(3) If $\vec{u} \neq \dots$ then $S = \{ \vec{u} \}$ is _____.

PROOF: Suppose $\vec{u} \neq \dots$
Suppose

Example Let

$$S = \left\{ \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 3 \\ -2 \\ 1 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 3 \\ 4 \\ -2 \\ 3 \end{bmatrix}, \vec{v}_4 = \begin{bmatrix} 2 \\ 2 \\ -1 \\ 2 \end{bmatrix} \right\}$$

Determine whether the set S is linearly dependent
or independent in \mathbb{R}^4 .

Consider the vector equation

$$(*) \quad x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 + x_4 \vec{v}_4 = \dots$$

where $x_1, x_2, x_3, x_4 \in \dots$

$$\Leftrightarrow x_1 \begin{bmatrix} 1 \\ -1 \\ 1 \\ \vdots \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 3 \\ -2 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ 4 \\ -2 \\ 3 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ 2 \\ -1 \\ 2 \end{bmatrix} =$$

$$\Leftrightarrow \begin{cases} x_1 + x_2 + 3x_3 + 2x_4 = 0 \\ -x_1 + 3x_2 + 4x_3 + 2x_4 = \dots \\ x_1 - 2x_2 - 2x_3 - x_4 = \dots \\ x_1 + x_2 + 3x_3 + 2x_4 = \dots \end{cases}$$

$$\Leftrightarrow \left[\begin{array}{cccc|c} 1 & & & & \\ -1 & & & & \\ & & & & \\ & & & & \end{array} \right]$$

$$\Leftrightarrow \left[\begin{array}{cccc|c} 1 & & & & \\ 0 & & & & \\ 0 & & & & \\ 0 & & & & \end{array} \right]$$

$$\Leftrightarrow \left[\begin{array}{cc|c} 1 & 1 & \\ 0 & 1 & \\ 0 & -3 & \\ 0 & 0 & \end{array} \right]$$

$$\Leftrightarrow \left[\begin{array}{cccc|c} 1 & 1 & 3 & 2 & 0 \\ 0 & 1 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \Leftrightarrow \begin{array}{l} x_1 = \\ x_2 = \\ x_3 = \end{array}$$

This system is _____
 _____ is a _____ variable.

So the system has _____ solutions
 and hence S is linearly _____.

One soln is $x_4 =$, $x_3 =$, $x_2 =$, $x_1 =$

So _____ =
 and observe that
 $\vec{v}_4 =$ _____

Proposition Let V be a vector space over F and
 suppose $S \subset V$. Then
 S is linearly dependent if and only if
 there is a vector in S that is _____
 _____ or _____ $\in S$.

PROOF

(\Rightarrow) Suppose S is linearly dependent.
 Then

Case 1 $n=1$.

Case 2 $n > 1$. Then

$$c_1 \vec{v}_1 =$$

$$\vec{v}_1 =$$

and \vec{v}_1 is

(\leftarrow)

Case 1 Suppose $\vec{v}_1 \in S$ is a

Case 2 Suppose $\vec{0} \in S$.

Theorem 1.6 Let V be a vector space over F and suppose $S_1 \subset S_2 \subset V$.

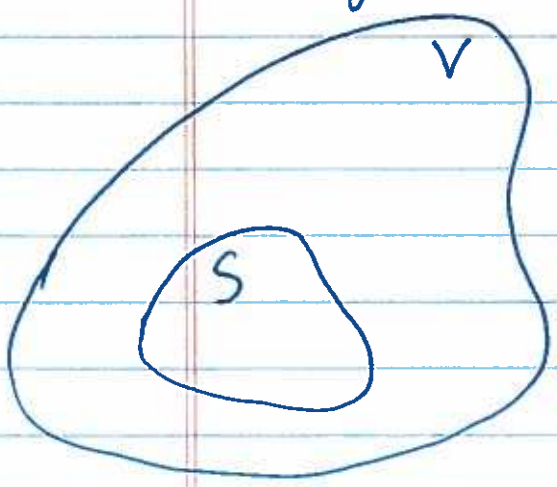
If S_1 is linearly ----- Non
 S_2 is linearly -----.

Proof: Suppose $S_1 \subset S_2 \subset V$, V is a vector space over F & S_1 is linearly dependent. So there are

Corollary Suppose V is a vector space over F & $S_1 \subset S_2 \subset V$.

If S_2 is linearly ----- Non
 S_1 is linearly -----.

Theorem 1.7 Let S be a linearly independent subset of a vector space V .



Let $\vec{v} \in V \setminus S$
is -----
Non

----- is
linearly dependent if and only
if $\vec{v} \in$ -----.

PROOF. Assume S is a linearly independent subset of vector space V and $\vec{v} \in V \setminus S$.

(\Rightarrow) Suppose $S \cup \{\vec{v}\}$ is linearly dependent. Then there are vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n \in S \cup \{\vec{v}\}$ and scalars c_1, c_2, \dots, c_n such that

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$
 Since S is linearly independent at least one $c_i \neq 0$. We may assume that (with loss of generality) that $c_1 \neq 0$ and

Case 1 $n=1$. Then

Case 2 $n > 1$. Then

$$c_1 \vec{v}_1 + \dots + c_n \vec{v}_n = \vec{0} \quad \text{and} \\ \vec{v}_1 = \vec{v} \quad \in S$$

since $\vec{v} \in S$

In both cases $\vec{v} \in S$

(\Leftarrow) Suppose $\vec{v} \in S$

Example Let

$$S = \left\{ \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} -1 \\ 2 \\ 2 \\ -1 \end{bmatrix}, \vec{v}_4 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix} \right\}$$

Determine whether S is linearly dependent or independent in \mathbb{R}^4 .

PROVING LINEAR INDEPENDENCE / DEPENDENCE

Let $S = \{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_n \} \subset V$ where V
is a vector space over F .

⊗ To prove S is linearly independent
assume

where

Then prove we must have

⊗ To prove S is linearly dependent
consider

(*)

and

EITHER

OR

show (*) has

VECTORS IN \mathbb{R}^3

Linearly independent

Linearly dependent

Linearly independent

Linearly dependent

1.6 Bases and Dimension

Definition Let $\mathcal{B} \subset V$ where V is a vector space over F . Then \mathcal{B} is a basis for V if

and

Theorem 1.8

Suppose $\mathcal{B} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} \subset V$ where V is a vector space over F . \mathcal{B} is a basis for V if and only if

every vector $\vec{v} \in V$ can be written

$$(*) \quad \vec{v} =$$

where \dots are the

scalars \dots are \dots .

PROOF:

(\Rightarrow) Suppose $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis for V . Then \mathcal{B}

Since \mathcal{B} spans V each vector $\vec{v} \in V$ can be written as a

$$\vec{v} =$$

where

$$\text{Suppose } \vec{v} =$$

is

$$\text{Then } \vec{v} - \vec{v} = \dots \text{ and} \\ = \vec{0}.$$

Thus

Hence

so that the _____ is _____.

(\Leftarrow) Suppose each $\vec{v} \in V$ can be written _____ as a _____ (*)

Then clearly V _____

Now suppose

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

where each _____

But

$$= \vec{0}$$

By _____ we have

$$c_1 = \dots, c_2 = \dots, \dots, c_n = \dots$$

and B is _____

Hence B is _____ \square

Examples

(1) _____ is a basis for $\{\vec{0}\}$ since _____ and _____

$$(2) \mathcal{E} = \left\{ \vec{e}_1 = \begin{bmatrix} \\ \\ \end{bmatrix}, \vec{e}_2 = \begin{bmatrix} \\ \\ \end{bmatrix}, \dots, \vec{e}_n = \begin{bmatrix} \\ \\ \end{bmatrix} \right\}$$

is a basis for F^n where F is a field.

NOTE $(\vec{e}_k)_j = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases}$

Hence $(\vec{e}_k)_j$ is the _____ component of \vec{e}_k

PROOF: Let $\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \in F^n$

Then $\vec{a} = \sum_{k=1}^n \dots \vec{e}_k$

since $(\vec{a})_j = \sum_{k=1}^n \dots$

$\dots = a_j$

for each $1 \leq j \leq n$. Therefore

$\mathcal{E} \dots F^n$

Now suppose $\sum_{k=1}^n x_k \vec{e}_k = \vec{0}$

where each $x_k \dots$. Then

$\left(\sum_{k=1}^n x_k \vec{e}_k \right)_j =$

$\sum_{k=1}^n \dots =$

ad for each $1 \leq j \leq n$. Hence \mathcal{E} is \dots
and

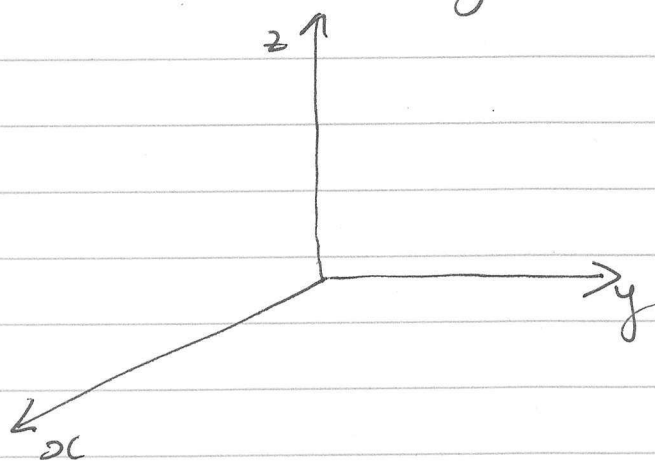
\mathcal{E} is a basis for F^n .

Note: \mathcal{E} is called the \dots basis for F^n .

Example

$$\left\{ \vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

is the standard basis for \mathbb{R}^3



$$\begin{aligned} \vec{e}_1 &= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \\ \vec{e}_2 &= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \\ \vec{e}_3 &= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

Example Determine whether the vectors

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

form a basis for \mathbb{R}^3 . Let $\vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3$.

Consider the vector eqn:

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 = \vec{v}$$



Now consider the vector eqn
 $\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 \vec{v}_3 = \dots$

Example

Let $n \geq 1$ (integer), and

$P_n(F) =$ set of polynomials in $P(F)$ with \dots

Then $P_n(F)$ is a subspace of \dots and

$\{ \dots \}$ is a basis for $P_n(F)$.

Also $\{ \dots \}$ is a basis for $P(F)$.

Example Find a basis for the vector space S of 2×2 symmetric matrices with real entries.

$$\text{Here } F = \text{---} \text{ and } S = \left. \begin{matrix} \text{---} \\ \text{---} \end{matrix} \right\}$$

Theorem 1.9 Let V be a vector space over a field F .

Suppose $S \subset V$ and $\text{Span}(S) = V$ and suppose S is a finite set. Then _____ is a basis for V , and V has a _____ basis.

PROOF: Suppose $S \subset V$, $\text{Span}(S) = V$ & S is a finite set.

Case 1 $S = \text{---}$ or --- .

Then $V = \text{---}$
and --- is a basis for V .

Case 2 $S \neq \dots$ and \dots ie S
contains \dots

Then $\{\vec{v}\} \subset S$ and $\{\vec{v}\}$ is

Consider all non-empty subsets $T \subset S$
which are \dots

Since S is finite choose a \dots BCS
(ie \dots) and B is \dots

If $B = S$ Then

Now suppose $B \subsetneq S$. We claim $S \subset \dots$
Suppose by way of contradiction that this claim
~~does not~~ does not hold; ie there is a \dots
such that \dots
Then

Let $B' = \dots$
Then B' is \dots by Theorem 1.7
since \dots
But $|B'|$

This contradicts \dots
Hence $S \subset \dots$ and
 $V = \text{Span}(S) \subset \dots \subset V$
and $V = \dots$
so that B is a \dots for V .

Example Let

$$W = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \in \mathbb{R}^4 : x_1 + x_2 + x_3 + x_4 = 0 \right\}.$$

$$\text{Let } S = \left\{ \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 2 \\ -2 \\ 0 \\ 0 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 2 \\ -1 \\ -1 \\ 0 \end{bmatrix}, \right. \\ \left. \vec{v}_4 = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix}, \vec{v}_5 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} \right\}.$$

It can be shown that

$$\text{Span}(S) = W.$$

Find a subset B of S which is a basis for W .
Consider the vector eqn

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 + x_4 \vec{v}_4 + x_5 \vec{v}_5 = \vec{0}$$



Theorem 1.10 (The Replacement Theorem)

Let V be a vector space over F .

Suppose G, L are finite subsets of V such that
 $V = \text{Span}(G)$, $|G| = n$,

L is linearly independent, and $|L| = m$.

Then

$m \leq n$, and there is a set $H \subset G$
 $|H| = m$ and $\text{Span}(H) = V$.

PROOF We proceed by induction on m . Let
If $m=0$ then then $L =$ and $\cap H =$
 $m=0 \leq$ and $\text{Span}(\quad) =$

Suppose the statement is true for a fixed integer m .
Let $L = \{\vec{v}_1, \dots, \vec{v}_m, \vec{v}_{m+1}\}$ be
 $V =$ and $|G| =$

Then $L' = \{\vec{v}_1, \dots\}$ is
and by the \dots there is a subset
 $X' = \{ \dots \}$ of G such that
 $\text{Span}(\quad) = \text{Span}(\quad) = \dots$
Hence

NOTE: $n - m > \dots$ otherwise \vec{v}_{m+1} would be
a linear combination of \dots
which would contradict \dots being linearly

Therefore $n - m \geq \dots$ and $n \geq \dots$.
Similarly at least one of the \dots
is \dots otherwise

$\vec{v}_{m+1} =$
and \dots is \dots
Suppose without loss of generality that $a_1 \neq 0$. Then
(*) $\vec{u}_1 =$

Let $H = \{ \dots \}$. Then
 $\vec{u}_1 \in \dots$ by \dots and
 $\{ \dots \} \subset \text{Span}(\quad)$.

$V = \text{Span}(\{ \dots \}) \subset \text{Span}(\dots) \subset \dots$
end

$V = \text{Span}(\dots), \mathcal{H} \subset \mathcal{G},$

$|\mathcal{H}| = \dots$ and

The theorem is true for \dots . The theorem follows by mathematical induction. \square

Corollary 1. Let V be a vector space with a finite basis. Then every basis for V has

PROOF Suppose V has a finite basis \mathcal{B} & $|\mathcal{B}| = n$.

Case 1 $n = 0$. Then $V = \{ \dots \}$ and \dots

Case 2 $n \geq 1$. Let $\mathcal{B} = \{ \vec{b}_1, \vec{b}_2, \dots, \vec{b}_n \}$, let $\mathcal{B}' = \{ \vec{b}_1, \vec{b}_2, \dots, \vec{b}_m \}$ be another basis.

Then \mathcal{B}' is \dots and $\text{Span}(\mathcal{B}) = V$.

~~By Theorem 10 (Replacement Theorem) any linearly independent subset of V has at most n vectors.~~

Let \mathcal{B}' be a basis for V . Then \mathcal{B}' is linearly independent. If \mathcal{B}' is infinite or has more than n vectors we can select a subset \mathcal{C} of exactly $n+1$ elements. $\mathcal{C} \subset \mathcal{B}'$.

\mathcal{C} is linearly independent since \mathcal{B}' is. By Theorem 10 (Replacement Thm). $|\mathcal{C}| = n+1 \dots$

since

This is a -----

Hence B' is ----- and $|B'|$ -----

Reversing the ----- and

we have $|B|$ -----

and therefore

Definition. A vector space V is finite dimensional if -----

In this case the dimension of V :=

and write -----

If ----- then

we say that V is infinite dimensional.

Examples

(1) $\dim \{0\} =$

(2) $\dim F^n =$

(3) $\dim P_n(F) =$

(4) $P(F)$ is

(5) $\dim M_{m \times n}(F) =$

(6) Let \mathbb{C} be the set of complex nos. (field).

\mathbb{C} is a vector space over \mathbb{C} .

A basis is ----- & $\dim_{\mathbb{C}} \mathbb{C} =$

(7) $\mathbb{C} = \{x+iy : x, y \in \mathbb{R}\}$ is a vector space over \mathbb{R} .

A basis is

and $\dim_{\mathbb{R}} \mathbb{C} =$

Corollary 2. Suppose V is a finite dimensional vector space over F and $\dim V = n$.

(a) Let G be finite and suppose $\text{span}(G) = V$.

Then $|G| =$ _____.

If _____ then G is a basis for V .

(b) Let

L be a linearly independent subset of V .

Then $|L| =$ _____.

If _____ then L is a basis for V .

(c) Suppose $L \subset V$ is linearly independent.

Then

L _____ to form a basis for V .

PROOF: Let B be a basis for V . and ~~suppose~~ $|B| =$ _____

(a) Suppose $G \subset V$, G is finite & $\text{span}(G) = V$.
By Theorem 1.10

since $|B| =$ _____ and B is _____.

Now suppose $|G| = n$.

By Theorem 1.9, some subset $G' \subset \dots$
is a \dots . But

$$|G'| = \dots \text{ since } \dots$$

This implies \dots since \dots

Hence G is a basis for V .

(b) Suppose $L \subset V$ and L is linearly independent.

Let L' be any finite subset of L .

Then L' is \dots and
by Theorem 1.10

$$|L'|$$

It follows that L is \dots and $|L| \dots$

Now suppose $|L| = n$. By Theorem 1.10

There is a subset \mathcal{H} of B (since $B \dots$)
containing exactly \dots vector such that

$$L \cup \mathcal{H} = \dots$$

So $L \dots$

and L is a basis for V .

(c) Suppose $L \subseteq V$ & L is linearly independent.

Then by (b),

$$|L| = m \text{ -----}$$

Since ----- and $|B| = \text{-----}$.

by Theorem 1.10 there is a subset H of -----

such that $|H| = \text{-----}$

and ----- spans V .

By part (a) $|L \cup H| \leq \text{-----}$.

end

$$|L \cup H| = \text{-----} \text{ and}$$

----- is a basis for V by part (a).

Hence L can be extended to a ~~basis~~ basis

□

Example

Let $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_4 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \vec{v}_5 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \in \mathbb{R}^4$

(i) Determine whether the vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3$ span \mathbb{R}^4

(ii) Determine whether the vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4, \vec{v}_5$ are linearly independent.

Theorem 1.11 Let W be a subspace of a finite dimensional vector space V . Then W is _____ and $\dim W$ _____.

~~PROOF:~~

If $\dim W$ _____ then _____.

PROOF: Let $\dim V = n$.

Case 1: $W = \{\vec{0}\}$.

Case 2 $W \neq \{\vec{0}\}$. Then W contains a vector $\vec{v} \neq$ _____. Then $\{\vec{v}\}$ is a _____ subset of W .

Any linearly independent subset of W is linearly independent in _____ and has _____ by Cor. 2(b). Therefore we may choose a maximal linearly independent set L such that $\{\vec{v}\} \subset L = \{\vec{v}_1, \dots, \vec{v}_k\} \subset W$

We will show that L is _____.

By Cor. 2(b),

$$|L| = k \text{ _____}$$

We claim that $\text{Span}(L) = W$.

Suppose by way of contradiction that

$$\text{Span}(L) \subsetneq W,$$

ie there is _____ such that _____.

Therefore _____ L and

_____ is linearly independent by
Theorem 1.7. But

_____ which contradicts the _____ of L .

Hence $\text{Span}(L) = W$ and L is _____.

Therefore $\dim(W) = \text{_____}$.

Now suppose $\dim W = \dim V = n$.

Let D be a basis for W . Then $|D| = n$
and D is linearly independent. By Cor. 2(b)

D is a basis for V since $|D| = |V| = n$ & D
is linearly independent.

Since D is a basis for W , $\text{Span}(D) = W$.

Since D is a basis for V , _____

and _____

□

Example Let

$$W = \left\{ \vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \end{bmatrix} \in F^5 : a_1 + a_3 + a_5 = 0, a_2 = a_4 \right\}$$

where F is a field. Then W is a subspace of F^5 .

Show that

$$B = \left\{ \vec{w}_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \vec{w}_2 = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \vec{w}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

is a basis for W . First

$\vec{w}_1 \in W$ since

$\vec{w}_2 \in W$ since

$\vec{w}_3 \in W$ since

and so $B \subset W$.

Suppose $x_1 \vec{w}_1 + x_2 \vec{w}_2 + x_3 \vec{w}_3 = \vec{0}$ where $x_1, x_2, x_3 \in F$.

Now suppose $\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \end{bmatrix} \in W$.

Then

cp.6r)

$$\vec{a} = \begin{bmatrix} a_3 \\ a_4 \\ a_5 \end{bmatrix} =$$

Hence $W =$
and thus B is a ---
and $\dim W = \text{---}$.