

Exposed points of matrix convex sets

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Noncommutative convexity – matrix convex sets

Definition: Let $K_n \subseteq M_n(V)$ for $n \in \mathbb{N}$ and denote $\mathbf{K} = (K_n)_{n \in \mathbb{N}}$.

1. A **matrix convex combination** of $A_1, \dots, A_k \in \mathbf{K}$ with $A_i \in K_{n_i}$ is an expression of the form

$$\sum_{i=1}^k \gamma_i^* A_i \gamma_i \in M_n(V),$$

where $\gamma_i \in \mathbb{M}_{n_i, n}$ satisfy $\sum_{i=1}^k \gamma_i^* \gamma_i = \mathbb{I}_n$.

2. The family \mathbf{K} is a **matrix convex set** if it is closed under formation of matrix convex combinations of its elements.

Morphisms – matrix affine maps

Definition: A **matrix affine map** $\Phi = (\Phi_r)_r$ between matrix convex sets \mathbf{K} and \mathbf{L} in the spaces V and W , respectively, is a sequence of linear maps $\Phi_r : M_r(V) \rightarrow M_r(W)$ that satisfy $\Phi_r(K_r) \subseteq L_r$ for all $r \in \mathbb{N}$ and

$$\Phi_r\left(\sum_{i=1}^k \gamma_i^* A_i \gamma_i\right) = \sum_{i=1}^k (\gamma_i^* \otimes \mathbb{I}_r) \Phi_{r_i}(A_i) (\gamma_i \otimes \mathbb{I}_r)$$

for all matrix convex combinations $\sum_{i=1}^k \gamma_i^* A_i \gamma_i$.

Motivation

Matrix extreme points

Definition: Let $\mathbf{K} = (K_n)_{n \in \mathbb{N}}$ be a matrix convex set and $A \in K_n$.

1. A matrix convex combination

$$A = \sum_{i=1}^k \gamma_i^* A_i \gamma_i \quad (1)$$

is **proper** if all the γ_i are surjective. In particular, $n \geq n_i$ for all i .

2. The point A is **matrix extreme** if any expression of the form (1) implies all the A_i are unitarily equivalent to A . Hence, $n_i = n$ for all i .

► Notation: $\text{mext}(\mathbf{K})$.

Well-known results

The Webster-Winkler matricial Krein-Milman theorem

Definition: Let $\mathbf{S} = (S_n)_{n \in \mathbb{N}}$ with $S_n \subseteq M_n(V)$. The smallest closed matrix convex set containing \mathbf{S} is called the **closed matrix convex hull** of \mathbf{S} and is denoted by $\overline{\text{mconv}} \mathbf{S}$.

Theorem (Webster-Winkler 99')

Let \mathbf{K} be a compact matrix convex set in a locally convex space V . Then $\text{mext } \mathbf{K} \neq \emptyset$ and

$$\mathbf{K} = \overline{\text{mconv}}(\text{mext } \mathbf{K}).$$

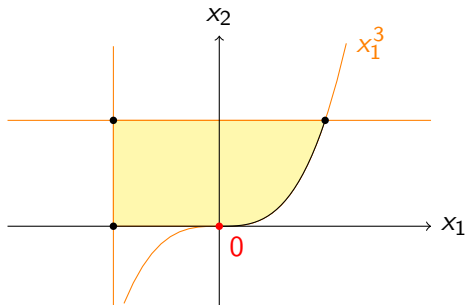
Exposed points

The Straszewicz theorem

Theorem (Straszewicz 35', Klee 58')

For any compact convex set K in a normed space V , $\text{exp}(K) \neq \emptyset$
and

$$K = \overline{\text{conv}}(\text{exp}(K)).$$



Matrix exposed points

Definition and basic properties

Definition: Let $\mathbf{K} = (K_n)_{n \in \mathbb{N}}$ be a matrix convex set in a dual vector space V . An element $A \in K_n$ is called a **matrix exposed point** of \mathbf{K} if there exist a continuous linear map $\Phi : V \rightarrow \mathbb{M}_n$ and a self-adjoint matrix $\alpha \in \mathbb{M}_n$ such that the following conditions hold:

- (a) for all positive integers r and $B \in K_r$ we have $\Phi_r(B) \preceq \alpha \otimes \mathbb{I}_r$;
- (b) $\{B \in K_n \mid \alpha \otimes \mathbb{I}_n - \Phi_n(B) \succeq 0 \text{ singular}\} = \{U^*AU \mid U \in \mathbb{M}_n \text{ unitary}\}$.

Properties:

- ▶ The matrix exposed points in K_1 coincide with the ordinary exposed points of K_1 .
- ▶ For $r < n$ and $B \in K_r$ the strict inequality $\Phi_r(B) \prec \alpha \otimes \mathbb{I}_r$ holds.

Matrix exposed points

Connection with matrix extreme points

Proposition (Kriel 19, Klep-Š)

Let $\mathbf{K} = (K_n)_{n \in \mathbb{N}}$ be a matrix convex set. Then:

- (a) Every matrix exposed point in K_n is ordinary exposed in K_n .
- (b) Any matrix exposed point is matrix extreme.
- (c) A point which is both exposed and matrix extreme, is a matrix exposed point.

Matrix exposed points

Connection with matrix extreme points (a)

(a) Every matrix exposed point in K_n is ordinary exposed in K_n .

Proof idea: form the compression functional

$$\phi(X) = v^*(\alpha \otimes \mathbb{I}_n - \Phi_n(X))v$$

for some $v \in \mathbb{C}^n \otimes \mathbb{C}^n$. But which v ?

Proposition (McCullough, Farenick)

Let $A \in K_n$ be a matrix exposed point with an exposing pair (Φ, α) . Then the following statements hold.

- (a) For any nonzero $x = \sum_{j=1}^n x_j \otimes e_j \in \mathbb{C}^n \otimes \mathbb{C}^n$ in the kernel of $\alpha \otimes \mathbb{I}_n - \Phi_n(A)$, the components x_1, \dots, x_n form a basis of \mathbb{C}^n .
- (b) The kernel of $\alpha \otimes \mathbb{I}_n - \Phi_n(A)$ is one-dimensional.

Matrix exposed points

Connection with matrix extreme points (c)

(c) A point which is both exposed and matrix extreme, is also matrix exposed.

Proof idea:

- ▶ A exposed $\implies \exists \varphi : M_n(V) \rightarrow \mathbb{R}$ and $a \in \mathbb{R}$ with $\varphi(A) = a$ and $\varphi|_{K_n \setminus \{A\}} < a$.
- ▶ Idea: use Effros-Winkler matricial separation techniques, but the separation happens over a real closed field (cf. Netzer-Thom separation theorem).
- ▶ A finiteness theorem gives domination of φ by a state $\rho : M_n \rightarrow \mathbb{C}$.
- ▶ Proceed by a GNS-type construction as in the proof of the matricial Hahn-Banach theorem.
- ▶ A matrix extreme $\implies A \notin \text{mconv}(K_n \setminus \{U^*AU \mid U \in \mathbb{U}_n\})$.
Used in the end to prove the separation properties of the obtained map.

Matrix exposed points

The matricial Straszewicz theorem

Theorem (Matrix Straszewicz, Kriel, Klep-Š)

Let \mathbf{K} be a compact matrix convex set in a normed vector space V . Then $\text{mexp } \mathbf{K} \neq \emptyset$ and

$$\mathbf{K} = \overline{\text{mconv}}(\text{mexp } \mathbf{K}).$$

Proof uses the Hartz-Lupini method of introducing an associated family of convex sets $\{\Gamma_n(\mathbf{K})\}_{n \in \mathbb{N}}$ to a matrix convex set $\mathbf{K} = (K_r)_{r \in \mathbb{N}}$ given by

$$\Gamma_n(\mathbf{K}) = \{(\gamma^* \gamma, \gamma^* A \gamma) \mid \gamma \in \mathbb{M}_{k,n}, \text{tr}(\gamma^* \gamma) = 1, k \in \mathbb{N}, A \in K_k\}.$$

Matrix exposed points

The matricial Straszewicz theorem – idea of the proof

Proposition (Klep-Š)

Let $\mathbf{K} = (K_m)_{m \in \mathbb{N}}$ be a matrix convex set and $A \in K_r$. Let $\gamma \in \mathbb{M}_{r,n}$ be a surjective matrix with $\text{tr}(\gamma^* \gamma) = 1$ such that the point $(\gamma^* \gamma, \gamma^* A \gamma)$ is exposed in $\Gamma_n(\mathbf{K})$. Then A is a matrix exposed point of \mathbf{K} .

Proof idea – as in the WW proof of the matricial Krein-Milman theorem:

use Hahn-Banach separation + the above Proposition to reduce to the classical Straszewicz-Klee theorem.

More is true - a density result

Proposition (Klep-Š)

Let \mathbf{K} be a compact matrix convex set in a normed vector space V . Then the matrix exposed points of \mathbf{K} are dense in the matrix extreme points of \mathbf{K} .

Proof is again reduction to the classical case using the sets $\Gamma_n(\mathbf{K})$.

Examples

Spectrahedra and matrix state spaces of separable unital C^* -algebras

Corollary

If all the extreme points of a matrix convex set \mathbf{K} are exposed, then all the matrix extreme points of \mathbf{K} are matrix exposed.

- ▶ This is, e.g., the case with free spectrahedra.
- ▶ But also with the **matrix state space** of any separable unital C^* -algebra \mathcal{A} . This is the family $\mathbf{UCP}(\mathcal{A}) = (\mathbf{UCP}_n(\mathcal{A}))_n$, where

$$\mathbf{UCP}_n(\mathcal{A}) = \{\Phi : \mathcal{A} \rightarrow \mathbb{M}_n \mid \Phi \text{ unital completely positive}\}.$$

It is a weak* compact matrix convex set in \mathcal{A}^* .

Examples

Matrix state spaces of separable unital C^* -algebras continued

- ▶ There is a linear bijection between $\mathbf{UCP}_n(\mathcal{A})$ and the state space of $M_n(\mathcal{A})$ sending any $\Phi : \mathcal{A} \rightarrow \mathbb{M}_n$ to

$$\begin{aligned}\tilde{\Phi} : M_n(\mathcal{A}) &\rightarrow \mathbb{C}, \\ \tilde{\Phi}(X) &= \frac{1}{n} \langle \Phi_n(X)e, e \rangle,\end{aligned}$$

where $e = e_1 \oplus \cdots \oplus e_n$ and $\{e_i\}_i$ is the standard basis of \mathbb{C}^n .

- ▶ In the state space of a separable unital C^* -algebra, extreme points are exposed (Alfsen).

Thank you!