

Smith normal forms of matrices associated with the Grassmann graphs of lines in $\text{PG}(n-1, q)$

Peter Sin, U. of Florida

UD Discrete Math Seminar
November 11th, 2016

Smith normal forms

Graphs from lines

Smith normal forms

Chip-firing game

Cross-characteristics

Defining characteristic

Critical groups of graphs

Graphs from lines

Smith normal forms

Chip-firing game

Cross-characteristics

Defining characteristic

Grassmann and skew lines graphs

$$q = p^t, p \text{ prime}, V \cong \mathbb{F}_q^n,$$

Grassmann and skew lines graphs

$q = p^t$, p prime, $V \cong \mathbb{F}_q^n$,

$\Gamma' = \Gamma'(n, q)$ Grassman graph, vertices are lines of $\text{PG}(V)$,
i.e. 2-diml subspaces of V . Two vertices lie on an edge iff
the subspaces are distinct and have nonzero intersection.

Grassmann and skew lines graphs

$q = p^t$, p prime, $V \cong \mathbb{F}_q^n$,

$\Gamma' = \Gamma'(n, q)$ Grassman graph, vertices are lines of $\text{PG}(V)$,
i.e. 2-diml subspaces of V . Two vertices lie on an edge iff
the subspaces are distinct and have nonzero intersection.

Γ the complementary graph, is the skew lines graph.

Strongly Regular Graphs

Definition

A strongly regular graph with parameters (v, k, λ, μ) is a k -regular graph such that

- any two adjacent vertices have λ neighbors in common;
and

- any two nonadjacent vertices have μ neighbors in common.

The adjacency matrix of a SRG has three eigenvalues k, r, s .

Strongly Regular Graphs

Definition

A strongly regular graph with parameters (v, k, λ, μ) is a k -regular graph such that

any two adjacent vertices have λ neighbors in common;
and

any two nonadjacent vertices have μ neighbors in common.

The adjacency matrix of a SRG has three eigenvalues k, r, s .

Γ' is a SRG $v = \begin{bmatrix} n \\ 2 \end{bmatrix}_q$, $k = q(q+1) \begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q$,
 $\lambda = \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q + q^2 - 2$, $\mu = (q+1)^2$, $r = \begin{bmatrix} n \\ 1 \end{bmatrix}_q$ and
 $s = (q+1) \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q$.

Strongly Regular Graphs

Definition

A strongly regular graph with parameters (v, k, λ, μ) is a k -regular graph such that

any two adjacent vertices have λ neighbors in common;
and

any two nonadjacent vertices have μ neighbors in common.

The adjacency matrix of a SRG has three eigenvalues k, r, s .

Γ' is a SRG $v = \begin{bmatrix} n \\ 2 \end{bmatrix}_q$, $k = q(q+1) \begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q$,
 $\lambda = \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q + q^2 - 2$, $\mu = (q+1)^2$, $r = \begin{bmatrix} n \\ 1 \end{bmatrix}_q$ and
 $s = (q+1) \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q$.

Γ is also a SRG. So we have two families of SRGs parametrized by n, p and t .

Critical groups of graphs

Graphs from lines

Smith normal forms

Chip-firing game

Cross-characteristics

Defining characteristic

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

$L(\mathcal{G}) = D(\mathcal{G}) - A(\mathcal{G})$, Laplacian matrix.

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

$L(\mathcal{G}) = D(\mathcal{G}) - A(\mathcal{G})$, Laplacian matrix.

The Smith normal forms of $A(\mathcal{G})$ and $L(\mathcal{G})$ are invariants of \mathcal{G} .

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

$L(\mathcal{G}) = D(\mathcal{G}) - A(\mathcal{G})$, Laplacian matrix.

The Smith normal forms of $A(\mathcal{G})$ and $L(\mathcal{G})$ are invariants of \mathcal{G} .

$S(\mathcal{G})$, the abelian group whose cyclic decomposition is given by the SNF of $A(\mathcal{G})$, (Smith group).

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

$L(\mathcal{G}) = D(\mathcal{G}) - A(\mathcal{G})$, Laplacian matrix.

The Smith normal forms of $A(\mathcal{G})$ and $L(\mathcal{G})$ are invariants of \mathcal{G} .

$S(\mathcal{G})$, the abelian group whose cyclic decomposition is given by the SNF of $A(\mathcal{G})$, (Smith group).

$K(\mathcal{G})$, the finite part of the abelian group whose cyclic decomposition is given by the SNF of $L(\mathcal{G})$ (critical group, sandpile group, jacobian).

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

$L(\mathcal{G}) = D(\mathcal{G}) - A(\mathcal{G})$, Laplacian matrix.

The Smith normal forms of $A(\mathcal{G})$ and $L(\mathcal{G})$ are invariants of \mathcal{G} .

$S(\mathcal{G})$, the abelian group whose cyclic decomposition is given by the SNF of $A(\mathcal{G})$, (Smith group).

$K(\mathcal{G})$, the finite part of the abelian group whose cyclic decomposition is given by the SNF of $L(\mathcal{G})$ (critical group, sandpile group, jacobian).

$|K(\mathcal{G})|$ = number of spanning trees (Kirchhoff's Matrix-tree Theorem).

Smith Normal form

$A(\mathcal{G})$, an adjacency matrix of a graph \mathcal{G} .

$L(\mathcal{G}) = D(\mathcal{G}) - A(\mathcal{G})$, Laplacian matrix.

The Smith normal forms of $A(\mathcal{G})$ and $L(\mathcal{G})$ are invariants of \mathcal{G} .

$S(\mathcal{G})$, the abelian group whose cyclic decomposition is given by the SNF of $A(\mathcal{G})$, (Smith group).

$K(\mathcal{G})$, the finite part of the abelian group whose cyclic decomposition is given by the SNF of $L(\mathcal{G})$ (critical group, sandpile group, jacobian).

$|K(\mathcal{G})|$ = number of spanning trees (Kirchhoff's Matrix-tree Theorem).

Survey article on SNFs in combinatorics by R. Stanley (JCTA 2016).

Critical groups of graphs

Graphs from lines

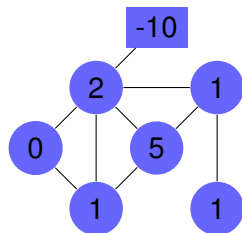
Smith normal forms

Chip-firing game

Cross-characteristics

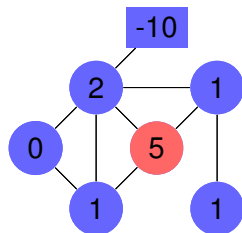
Defining characteristic

Rules



A *configuration* on the graph \mathcal{G} is an assignment of a nonnegative integer $s(v)$ to each round vertex v and $-\sum_v s(v)$ to the square vertex.

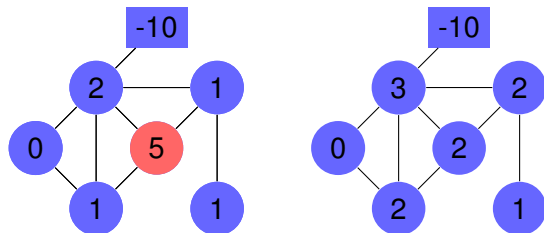
Rules



A *configuration* on the graph \mathcal{G} is an assignment of a nonnegative integer $s(v)$ to each round vertex v and $-\sum_v s(v)$ to the square vertex.

A round vertex v can be fired if it has at least $\deg(v)$ chips.

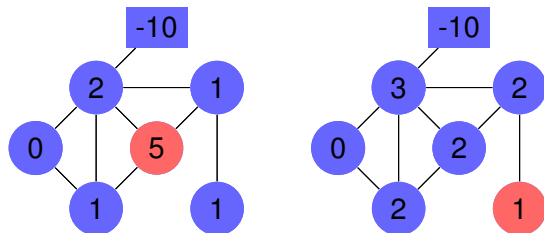
Rules



A *configuration* on the graph \mathcal{G} is an assignment of a nonnegative integer $s(v)$ to each round vertex v and $-\sum_v s(v)$ to the square vertex.

A round vertex v can be fired if it has at least $\deg(v)$ chips.

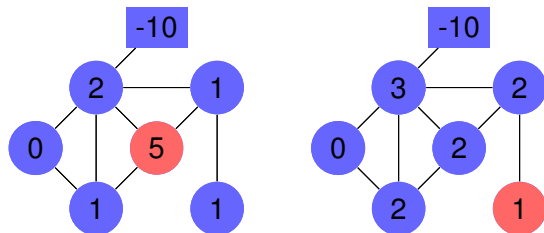
Rules



A *configuration* on the graph \mathcal{G} is an assignment of a nonnegative integer $s(v)$ to each round vertex v and $-\sum_v s(v)$ to the square vertex.

A round vertex v can be fired if it has at least $\deg(v)$ chips.

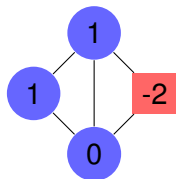
Rules



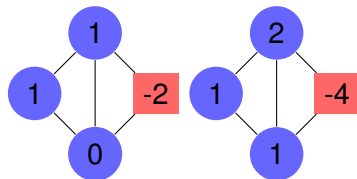
A *configuration* on the graph \mathcal{G} is an assignment of a nonnegative integer $s(v)$ to each round vertex v and $-\sum_v s(v)$ to the square vertex.

A round vertex v can be fired if it has at least $\deg(v)$ chips. The square vertex is fired only when no others can be fired.

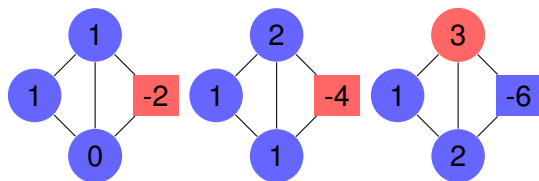
Example game



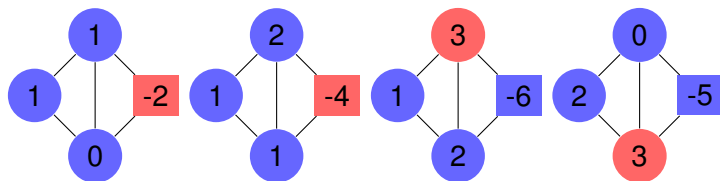
Example game



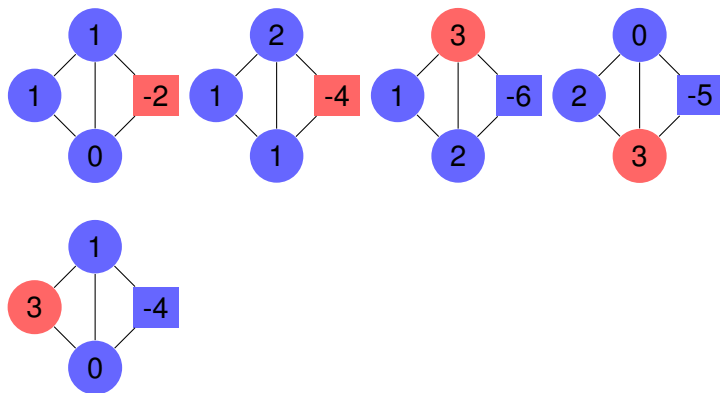
Example game



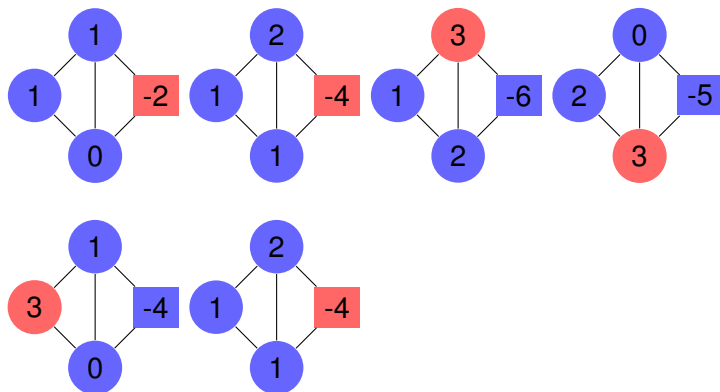
Example game



Example game



Example game



Relation with Laplacian

Start with a configuration s and fire vertices in a sequence where each vertex v is fired $x(v)$ times, ending up with configuration s' .

Relation with Laplacian

Start with a configuration s and fire vertices in a sequence where each vertex v is fired $x(v)$ times, ending up with configuration s' .

$$s'(v) = s(v) - x(v) \deg(v) + \sum_{(v,w) \in E} x(w)$$

Relation with Laplacian

Start with a configuration s and fire vertices in a sequence where each vertex v is fired $x(v)$ times, ending up with configuration s' .

$$s'(v) = s(v) - x(v) \deg(v) + \sum_{(v,w) \in E} x(w)$$

$$s' = s - L(\mathcal{G})x.$$

Relation with Laplacian

Start with a configuration s and fire vertices in a sequence where each vertex v is fired $x(v)$ times, ending up with configuration s' .

$$s'(v) = s(v) - x(v) \deg(v) + \sum_{(v,w) \in E} x(w)$$

$$s' = s - L(\mathcal{G})x.$$

A configuration is *stable* if no round vertex can be fired, *recurrent* if there is a sequence of firings leading back to the same configuration, *critical* if recurrent and stable.

Theorem

(Dhar, Björner-Lovász, Biggs, Gabrielov,...) Consider the chip-firing game on a connected graph \mathcal{G} .

Any starting configuration leads to a unique critical configuration.

The set of critical configurations has a natural group operation making it isomorphic to the critical group $K(\mathcal{G})$.

$GL(n, q)$ -Permutation modules

We (Ducey-S) compute the SNF for $A = A(\Gamma(n, q))$,
 $L = L(\Gamma(n, q))$, $A' = A(\Gamma'(n, q))$, $L' = L(\Gamma'(n, q))$.

$GL(n, q)$ -Permutation modules

We (Ducey-S) compute the SNF for $A = A(\Gamma(n, q))$,
 $L = L(\Gamma(n, q))$, $A' = A(\Gamma'(n, q))$, $L' = L(\Gamma'(n, q))$.

\mathcal{L}_r , the set of r -diml. subspaces of V .

$GL(n, q)$ -Permutation modules

We (Ducey-S) compute the SNF for $A = A(\Gamma(n, q))$,
 $L = L(\Gamma(n, q))$, $A' = A(\Gamma'(n, q))$, $L' = L(\Gamma'(n, q))$.

\mathcal{L}_r , the set of r -diml. subspaces of V .

A and L define $\mathbb{Z} GL(n, q)$ -module homomorphisms

$$A, L : \mathbb{Z}^{\mathcal{L}_2} \rightarrow \mathbb{Z}^{\mathcal{L}_2}$$

$GL(n, q)$ -Permutation modules

We (Ducey-S) compute the SNF for $A = A(\Gamma(n, q))$,
 $L = L(\Gamma(n, q))$, $A' = A(\Gamma'(n, q))$, $L' = L(\Gamma'(n, q))$.

\mathcal{L}_r , the set of r -diml. subspaces of V .

A and L define $\mathbb{Z} GL(n, q)$ -module homomorphisms

$$A, L : \mathbb{Z}^{\mathcal{L}_2} \rightarrow \mathbb{Z}^{\mathcal{L}_2}$$

SNF can be computed one prime at a time (elementary divisors).

$GL(n, q)$ -Permutation modules

We (Ducey-S) compute the SNF for $A = A(\Gamma(n, q))$,
 $L = L(\Gamma(n, q))$, $A' = A(\Gamma'(n, q))$, $L' = L(\Gamma'(n, q))$.

\mathcal{L}_r , the set of r -diml. subspaces of V .

A and L define $\mathbb{Z} GL(n, q)$ -module homomorphisms

$$A, L : \mathbb{Z}^{\mathcal{L}_2} \rightarrow \mathbb{Z}^{\mathcal{L}_2}$$

SNF can be computed one prime at a time (elementary divisors).

Fix prime ℓ $M = \mathbb{Z}_\ell^{\mathcal{L}_2}$, $\overline{M} = \mathbb{F}_\ell^{\mathcal{L}_2}$, $\alpha \in \{A, L\}$.

GL(n, q)-Permutation modules

We (Ducey-S) compute the SNF for $A = A(\Gamma(n, q))$,
 $L = L(\Gamma(n, q))$, $A' = A(\Gamma'(n, q))$, $L' = L(\Gamma'(n, q))$.

\mathcal{L}_r , the set of r -diml. subspaces of V .

A and L define \mathbb{Z} GL(n, q)-module homomorphisms

$$A, L : \mathbb{Z}^{\mathcal{L}_2} \rightarrow \mathbb{Z}^{\mathcal{L}_2}$$

SNF can be computed one prime at a time (elementary divisors).

Fix prime ℓ $M = \mathbb{Z}_\ell^{\mathcal{L}_2}$, $\overline{M} = \mathbb{F}_\ell^{\mathcal{L}_2}$, $\alpha \in \{A, L\}$.



$$M = M_0 \supseteq M_1 \supseteq \cdots \supseteq M_r = \text{Ker}(\alpha) \supseteq 0.$$

$$\overline{M} = \overline{M}_0 \supseteq \overline{M}_1 \supseteq \cdots \supseteq \overline{M}_r = \overline{\text{Ker}(\alpha)} \supseteq 0.$$

$e_i = e_i(\alpha) :=$ multiplicity of ℓ^i as an elementary divisor of α .
($e_0 = \text{rank}(\overline{\alpha})$).

$e_i = e_i(\alpha) :=$ multiplicity of ℓ^i as an elementary divisor of α .
($e_0 = \text{rank}(\overline{\alpha})$).

$$\dim \overline{M}_a = 1 + \sum_{i \geq a} e_i.$$

$e_i = e_i(\alpha) :=$ multiplicity of ℓ^i as an elementary divisor of α .
($e_0 = \text{rank}(\bar{\alpha})$).

$$\dim \bar{M}_a = 1 + \sum_{i \geq a} e_i.$$

All quotients $\bar{M}_a / \bar{M}_{a+1}$ are $\mathbb{F}_\ell \text{GL}(n, q)$ -modules, so the number of nonzero e_i is at most the composition length of \bar{M} as a $\mathbb{F}_\ell \text{GL}(n, q)$ -module.

Critical groups of graphs

Graphs from lines

Smith normal forms

Chip-firing game

Cross-characteristics

Defining characteristic

ℓ -modular representations of $GL(n, q)$

$$\ell \neq p$$

ℓ -modular representations of $GL(n, q)$

$$\ell \neq p$$

Theory due to G. D. James.

ℓ -modular representations of $GL(n, q)$

$$\ell \neq p$$

Theory due to G. D. James.

M is a q -analogue of the \mathbb{F}_ℓ -permutation module of subsets of size 2 in a set of size n .

ℓ -modular representations of $GL(n, q)$

$$\ell \neq p$$

Theory due to G. D. James.

M is a q -analogue of the \mathbb{F}_ℓ -permutation module of subsets of size 2 in a set of size n .

M has 3 isomorphism types of composition factors.

ℓ -modular representations of $GL(n, q)$

$$\ell \neq p$$

Theory due to G. D. James.

M is a q -analogue of the \mathbb{F}_ℓ -permutation module of subsets of size 2 in a set of size n .

M has 3 isomorphism types of composition factors.

The composition length is ≤ 6 and does not grow with n or t or p , but depends on certain divisibility conditions.

ℓ -modular representations of $GL(n, q)$

$$\ell \neq p$$

Theory due to G. D. James.

M is a q -analogue of the \mathbb{F}_ℓ -permutation module of subsets of size 2 in a set of size n .

M has 3 isomorphism types of composition factors.

The composition length is ≤ 6 and does not grow with n or t or p , but depends on certain divisibility conditions.

Based on James results, it is easy to work out the submodule structure of \overline{M} in all cases.

		$\ell \nmid \begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q$	$\ell \mid \begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q$
$\ell \nmid q+1$	$\ell \nmid \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q$	$M = \mathbb{F}_\ell \oplus D_1 \oplus D_2$	$M = \mathbb{F}_\ell \oplus \begin{matrix} D_1 \\ D_2 \\ D_1 \end{matrix}$
	$\ell \mid \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q$	$M = \begin{matrix} \mathbb{F}_\ell \\ D_1 \oplus D_2 \\ \mathbb{F}_\ell \end{matrix}$	N/A
$\ell \mid q+1$	$\ell \nmid \lfloor \frac{n-1}{2} \rfloor$	$M = \mathbb{F}_\ell \oplus D_1 \oplus D_2$	N/A
	$\ell \mid \lfloor \frac{n-1}{2} \rfloor$	$M = \begin{matrix} \mathbb{F}_\ell \\ D_1 \oplus D_2 \\ \mathbb{F}_\ell \end{matrix}$	N/A

Table : $\ell \nmid \binom{n}{1}_q$

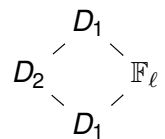
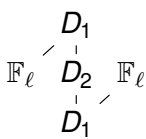
	$\ell \nmid \begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q$	$\ell \mid \begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q$	
$\ell \nmid q+1$ $\ell \nmid \begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q$	\mathbb{F}_ℓ $M = D_1 \oplus D_2$ \mathbb{F}_ℓ	N/A	
$\ell \mid q+1$ $\ell \nmid \lfloor \frac{n-1}{2} \rfloor$	N/A	$\ell \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ $M = \mathbb{F}_\ell \oplus D_2$ 	$\ell \mid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ $M = \mathbb{F}_\ell$ 
$\ell \mid q+1$ $\ell \mid \lfloor \frac{n-1}{2} \rfloor$	N/A	D_1 \mathbb{F}_ℓ $M = \mathbb{F}_\ell \oplus D_2$ \mathbb{F}_ℓ D_1	

Table : $\ell \mid \begin{pmatrix} n \\ 1 \end{pmatrix}_q$

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2} - 1}{q^2 - 1}$.

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2}-1}{q^2-1}$.

r has multiplicity $f = \begin{bmatrix} n \\ 1 \end{bmatrix}_q - 1$, s has multiplicity
 $g = \begin{bmatrix} n \\ 2 \end{bmatrix}_q - \begin{bmatrix} n \\ 1 \end{bmatrix}_q$.

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2} - 1}{q^2 - 1}$.

r has multiplicity $f = \begin{bmatrix} n \\ 1 \end{bmatrix}_q - 1$, s has multiplicity
 $g = \begin{bmatrix} n \\ 2 \end{bmatrix}_q - \begin{bmatrix} n \\ 1 \end{bmatrix}_q$.

Let $a = v_\ell(q + 1)$, $b = v_\ell(qh - 1)$ and $c = v_\ell(h)$.

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2} - 1}{q^2 - 1}$.

r has multiplicity $f = \begin{bmatrix} n \\ 1 \end{bmatrix}_q - 1$, s has multiplicity
 $g = \begin{bmatrix} n \\ 2 \end{bmatrix}_q - \begin{bmatrix} n \\ 1 \end{bmatrix}_q$.

Let $a = v_\ell(q + 1)$, $b = v_\ell(qh - 1)$ and $c = v_\ell(h)$.

$\ell \mid h$ if and only if $\ell \mid \frac{n-2}{2}$

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2} - 1}{q^2 - 1}$.

r has multiplicity $f = \begin{bmatrix} n \\ 1 \end{bmatrix}_q - 1$, s has multiplicity
 $g = \begin{bmatrix} n \\ 2 \end{bmatrix}_q - \begin{bmatrix} n \\ 1 \end{bmatrix}_q$.

Let $a = v_\ell(q + 1)$, $b = v_\ell(qh - 1)$ and $c = v_\ell(h)$.

$\ell \mid h$ if and only if $\ell \mid \frac{n-2}{2}$

$\gcd(h, qh - 1) = 1$, so either $c = 0$ or $b = 0$.

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2} - 1}{q^2 - 1}$.

r has multiplicity $f = \begin{bmatrix} n \\ 1 \end{bmatrix}_q - 1$, s has multiplicity
 $g = \begin{bmatrix} n \\ 2 \end{bmatrix}_q - \begin{bmatrix} n \\ 1 \end{bmatrix}_q$.

Let $a = v_\ell(q + 1)$, $b = v_\ell(qh - 1)$ and $c = v_\ell(h)$.

$\ell \mid h$ if and only if $\ell \mid \frac{n-2}{2}$

$\gcd(h, qh - 1) = 1$, so either $c = 0$ or $b = 0$.

$b = 0$ if and only if $\ell \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$.

Example: $\ell \mid q + 1$, n even

Assume $\ell \mid q + 1$, n even.

Then $k = q(q + 1)^2 h$, $r = (q + 1)(qh - 1)$, $s = -(q + 1)$,
where $h := \frac{q^{n-2} - 1}{q^2 - 1}$.

r has multiplicity $f = \begin{bmatrix} n \\ 1 \end{bmatrix}_q - 1$, s has multiplicity
 $g = \begin{bmatrix} n \\ 2 \end{bmatrix}_q - \begin{bmatrix} n \\ 1 \end{bmatrix}_q$.

Let $a = v_\ell(q + 1)$, $b = v_\ell(qh - 1)$ and $c = v_\ell(h)$.

$\ell \mid h$ if and only if $\ell \mid \frac{n-2}{2}$

$\gcd(h, qh - 1) = 1$, so either $c = 0$ or $b = 0$.

$b = 0$ if and only if $\ell \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$.

We'll look at the case $c = 0$ and $b = 0$. Then

$v_\ell(r) = v_\ell(s) = a$ and $v_\ell(|S(\Gamma)|) = af + ag + 2a$

Example: $\ell \mid q + 1$, n even, $v_\ell(r) = v_\ell(s) = a$

$$M = \mathbb{Z}_\ell \mathbf{1} \oplus Y.$$

Example: $\ell \mid q + 1$, n even, $v_\ell(r) = v_\ell(s) = a$

$$M = \mathbb{Z}_\ell \mathbf{1} \oplus Y.$$

On $Y = \text{Ker}(J)$ we have

$$A'(A' - (r + s)I) = -rsl.$$

Example: $\ell \mid q + 1$, n even, $v_\ell(r) = v_\ell(s) = a$

$$M = \mathbb{Z}_\ell \mathbf{1} \oplus Y.$$

On $Y = \text{Ker}(J)$ we have

$$A'(A' - (r + s)I) = -rsl.$$

This shows that $(A' - (r + s)I)(Y) \subseteq M_{2a} \cap Y$, so as $\ell \mid (r + s)$, $\overline{A'}(\overline{Y}) \subseteq \overline{M_{2a} \cap Y}$.

Example: $\ell \mid q + 1$, n even, $v_\ell(r) = v_\ell(s) = a$

$$M = \mathbb{Z}_\ell \mathbf{1} \oplus Y.$$

On $Y = \text{Ker}(J)$ we have

$$A'(A' - (r + s)I) = -rsI.$$

This shows that $(A' - (r + s)I)(Y) \subseteq M_{2a} \cap Y$, so as $\ell \mid (r + s)$, $\overline{A'}(\overline{Y}) \subseteq \overline{M_{2a} \cap Y}$.

$\overline{A'}(\overline{Y})$ is nonzero, so it has D_1 as a composition factor.

Example: $\ell \mid q + 1$, n even, $v_\ell(r) = v_\ell(s) = a$

$$M = \mathbb{Z}_\ell \mathbf{1} \oplus Y.$$

On $Y = \text{Ker}(J)$ we have

$$A'(A' - (r + s)I) = -rsI.$$

This shows that $(A' - (r + s)I)(Y) \subseteq M_{2a} \cap Y$, so as $\ell \mid (r + s)$, $\overline{A'}(\overline{Y}) \subseteq \overline{M_{2a} \cap Y}$.

$\overline{A'}(\overline{Y})$ is nonzero, so it has D_1 as a composition factor.

$\dim \overline{M_{2a} \cap Y} \geq f - 1$ and so $\dim \overline{M_{2a}} \geq f$.

Example: $\ell \mid q + 1$, n even, $v_\ell(r) = v_\ell(s) = a$

$$M = \mathbb{Z}_\ell \mathbf{1} \oplus Y.$$

On $Y = \text{Ker}(J)$ we have

$$A'(A' - (r + s)I) = -rsI.$$

This shows that $(A' - (r + s)I)(Y) \subseteq M_{2a} \cap Y$, so as $\ell \mid (r + s)$, $\overline{A'}(\overline{Y}) \subseteq \overline{M_{2a} \cap Y}$.

$\overline{A'}(\overline{Y})$ is nonzero, so it has D_1 as a composition factor.

$\dim \overline{M_{2a} \cap Y} \geq f - 1$ and so $\dim \overline{M_{2a}} \geq f$.

Further analysis of A' and structure of \overline{M} shows $\dim \overline{M}_a \geq g + 2$.

We have $\dim \overline{M}_{2a} \geq f$, $\dim \overline{M}_a \geq g + 2$.

We have $\dim \overline{M}_{2a} \geq f$, $\dim \overline{M}_a \geq g + 2$.



$$\begin{aligned} a(f + g) + 2a &= v_\ell(|S(\Gamma)|) = \sum_{i \geq 0} i e_i \\ &\geq \sum_{a \leq i < 2a} i e_i + \sum_{i \geq 2a} i e_i \\ &\geq a \sum_{a \leq i < 2a} e_i + 2a \sum_{i \geq 2a} e_i \\ &\geq a(\dim \overline{M}_a - \dim \overline{M}_{2a}) + 2a \dim \overline{M}_{2a} \\ &\geq a(g + 2) + af. \end{aligned}$$

Therefore, equality holds throughout, and it follows that $e_0 = f - 1$, $e_a = g - f + 2$, $e_{2a} = f$ (and $e_i = 0$ otherwise).

Critical groups of graphs

Graphs from lines

Smith normal forms

Chip-firing game

Cross-characteristics

Defining characteristic

Here the number of composition factors of \overline{M} grows like n^t ,
where $q = p^t$.

Here the number of composition factors of \overline{M} grows like n^t , where $q = p^t$.

But from the eigenvalues, L' has no p -elementary divisors.

Here the number of composition factors of \overline{M} grows like n^t , where $q = p^t$.

But from the eigenvalues, L' has no p -elementary divisors.

For A' , we can see that only k is divisible by p , so $S(\Gamma')$ is cyclic of order p^t .

Here the number of composition factors of \overline{M} grows like n^t , where $q = p^t$.

But from the eigenvalues, L' has no p -elementary divisors.

For A' , we can see that only k is divisible by p , so $S(\Gamma')$ is cyclic of order p^t .

- The skew lines matrices A and L are much harder but much of the difficulty was handled in earlier work for the case $n = 4$ (Brouwer-Ducey-S.)

Here the number of composition factors of \overline{M} grows like n^t , where $q = p^t$.

But from the eigenvalues, L' has no p -elementary divisors.

For A' , we can see that only k is divisible by p , so $S(\Gamma')$ is cyclic of order p^t .

- ▶ The skew lines matrices A and L are much harder but much of the difficulty was handled in earlier work for the case $n = 4$ (Brouwer-Ducey-S.)
- ▶ Note $A \equiv -L \pmod{p^{4t}}$, so just consider A .

Example

Table : The elementary divisors of the incidence matrix of lines vs. lines in $\text{PG}(3, 9)$, where two lines are incident when skew.

Elem. Div.	1	3	3^2	3^4	3^5	3^6	3^8
Multiplicity	361	256	6025	202	256	361	1

For $n = 4$ we have

$$A(A + q(q - 1)I) = q^3I + q^3(q - 1)J,$$

For $n = 4$ we have

$$A(A + q(q - 1)I) = q^3I + q^3(q - 1)J,$$

For general n , we have

$$\begin{aligned} & A(A + q\left(\begin{bmatrix} n-2 \\ 1 \end{bmatrix}_q - 2\right)I) \\ &= q^3\left(\begin{bmatrix} n-3 \\ 1 \end{bmatrix}_q\right)I + q^3 \frac{\left(\begin{bmatrix} n-3 \\ 1 \end{bmatrix}_q \left(\left(\begin{bmatrix} n-1 \\ 1 \end{bmatrix}_q - (q+2)\right)\right)}{q+1} J, \end{aligned}$$

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}_2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}_2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}, \text{ so } e_{4t} \geq 1.$$

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}_2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}, \text{ so } e_{4t} \geq 1.$$

We have

$$A|_Y [A|_Y - qz_1 I] = q^3 z_2 I,$$

where z_1, z_2 are units in \mathbb{Z}_p .

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}_2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}$, so $e_{4t} \geq 1$.

We have

$$A|_Y [A|_Y - qz_1 I] = q^3 z_2 I,$$

where z_1, z_2 are units in \mathbb{Z}_p .

- This equation implies:

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}_2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}$, so $e_{4t} \geq 1$.

We have

$$A|_Y[A|_Y - qz_1 I] = q^3 z_2 I,$$

where z_1, z_2 are units in \mathbb{Z}_p .

► This equation implies:

1. $A|_Y$ has no elementary divisors p^i for $i > 3t$.

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}_2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}$, so $e_{4t} \geq 1$.

We have

$$A|_Y[A|_Y - qz_1 I] = q^3 z_2 I,$$

where z_1, z_2 are units in \mathbb{Z}_p .

► This equation implies:

1. $A|_Y$ has no elementary divisors p^i for $i > 3t$.
2. $e_i = e_{3t-i}$ $0 \leq i < t$.

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}^2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}$, so $e_{4t} \geq 1$.

We have

$$A|_Y[A|_Y - qz_1 I] = q^3 z_2 I,$$

where z_1, z_2 are units in \mathbb{Z}_p .

► This equation implies:

1. $A|_Y$ has no elementary divisors p^i for $i > 3t$.
2. $e_i = e_{3t-i}$ $0 \leq i < t$.
3. $e_i = 0$ unless $0 \leq i \leq t$ or $2t \leq i \leq 3t$.

Reductions using SRG equation

$p \nmid \begin{bmatrix} n \\ 2 \end{bmatrix}_q$ so

$$\mathbb{Z}_p^{\mathcal{L}^2} = \mathbb{Z}_p \mathbf{1} \oplus Y, \quad Y = \text{Ker}(J)$$

$A(\mathbf{1}) = k\mathbf{1} = q^4 \begin{bmatrix} n-2 \\ 2 \end{bmatrix}_q \mathbf{1}$, so $e_{4t} \geq 1$.

We have

$$A|_Y[A|_Y - qz_1 I] = q^3 z_2 I,$$

where z_1, z_2 are units in \mathbb{Z}_p .

► This equation implies:

1. $A|_Y$ has no elementary divisors p^i for $i > 3t$.
2. $e_i = e_{3t-i}$ $0 \leq i < t$.
3. $e_i = 0$ unless $0 \leq i \leq t$ or $2t \leq i \leq 3t$.
4. Once we have e_i $0 \leq i < t$ we have them all.

Reduction to point-line incidence

$A_{r,s} :=$ the skewness matrix of r -subspaces vs. s -subspaces of V . So $A = A_{2,2}$.

Reduction to point-line incidence

$A_{r,s}$:= the skewness matrix of r -subspaces vs. s -subspaces of V . So $A = A_{2,2}$.

$$-A_{r,s} \equiv A_{r,1} A_{1,s} \pmod{p^t}$$

Reduction to point-line incidence

$A_{r,s}$:= the skewness matrix of r -subspaces vs. s -subspaces of V . So $A = A_{2,2}$.

$$-A_{r,s} \equiv A_{r,1} A_{1,s} \pmod{p^t}$$

Hence $e_i(A_{r,s}) = e_i(A_{r,1} A_{1,s})$ for $i < t$.

Reduction to point-line incidence

$A_{r,s}$:= the skewness matrix of r -subspaces vs. s -subspaces of V . So $A = A_{2,2}$.

$$-A_{r,s} \equiv A_{r,1} A_{1,s} \pmod{p^t}$$

Hence $e_i(A_{r,s}) = e_i(A_{r,1} A_{1,s})$ for $i < t$.

The p -elementary divisors for $A_{r,1}$ (and $A_{1,r}$) were computed by Chandler-Sin-Xiang (2006).

Reduction to point-line incidence

$A_{r,s}$:= the skewness matrix of r -subspaces vs. s -subspaces of V . So $A = A_{2,2}$.

$$-A_{r,s} \equiv A_{r,1} A_{1,s} \pmod{p^t}$$

Hence $e_i(A_{r,s}) = e_i(A_{r,1} A_{1,s})$ for $i < t$.

The p -elementary divisors for $A_{r,1}$ (and $A_{1,r}$) were computed by Chandler-Sin-Xiang (2006).

Nontrivial to relate p -elementary divisors of $A_{r,1}$ and $A_{1,s}$ to those of $A_{r,1} A_{1,s}$.

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for $0 \leq i \leq t-1$,

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for
 $0 \leq i \leq t-1,$
 $1 \leq s_i \leq n-1,$

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for
 $0 \leq i \leq t-1$,
 $1 \leq s_i \leq n-1$,
 $0 \leq ps_{i+1} - s_i \leq (p-1)n$,

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for
 $0 \leq i \leq t-1$,
 $1 \leq s_i \leq n-1$,
 $0 \leq ps_{i+1} - s_i \leq (p-1)n$,

The poset \mathcal{H} describes the submodule structure of $\mathbb{F}_q^{\mathcal{L}^1}$ under the action of $\mathrm{GL}(n, q)$. (Bardoe-S (2000)).

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for $0 \leq i \leq t-1$,
 $1 \leq s_i \leq n-1$,
 $0 \leq ps_{i+1} - s_i \leq (p-1)n$,

The poset \mathcal{H} describes the submodule structure of $\mathbb{F}_q^{\mathcal{L}_1}$ under the action of $\mathrm{GL}(n, q)$. (Bardoe-S (2000)).

- ▶ For $\vec{s} = (s_0, \dots, s_{t-1}) \in \mathcal{H}$ define $d(\vec{s})$ as follows.

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for $0 \leq i \leq t-1$,
 $1 \leq s_i \leq n-1$,
 $0 \leq ps_{i+1} - s_i \leq (p-1)n$,

The poset \mathcal{H} describes the submodule structure of $\mathbb{F}_q^{\mathcal{L}_1}$ under the action of $GL(n, q)$. (Bardoe-S (2000)).

- ▶ For $\vec{s} = (s_0, \dots, s_{t-1}) \in \mathcal{H}$ define $d(\vec{s})$ as follows.
Set $\lambda_i = ps_{i+1} - s_i$ ($0 \leq i \leq t-1$ subscripts mod t).

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for $0 \leq i \leq t-1$,
 $1 \leq s_i \leq n-1$,
 $0 \leq ps_{i+1} - s_i \leq (p-1)n$,

The poset \mathcal{H} describes the submodule structure of $\mathbb{F}_q^{\mathcal{L}^1}$ under the action of $GL(n, q)$. (Bardoe-S (2000)).

- ▶ For $\vec{s} = (s_0, \dots, s_{t-1}) \in \mathcal{H}$ define $d(\vec{s})$ as follows.
Set $\lambda_i = ps_{i+1} - s_i$ ($0 \leq i \leq t-1$ subscripts mod t).
 $d(\vec{s}) = \prod_{i=0}^{t-1} d_{\lambda_i}$, where $d_k :=$ coefficient of x^k in the expansion of $(1 + x + \dots + x^{p-1})^n$

The poset \mathcal{H}

- ▶ $\mathcal{H} :=$ the set of tuples $\{\vec{s} = (s_0, \dots, s_{t-1})$ such that, for $0 \leq i \leq t-1$,
 $1 \leq s_i \leq n-1$,
 $0 \leq ps_{i+1} - s_i \leq (p-1)n$,

The poset \mathcal{H} describes the submodule structure of $\mathbb{F}_q^{\mathcal{L}_1}$ under the action of $GL(n, q)$. (Bardoe-S (2000)).

- ▶ For $\vec{s} = (s_0, \dots, s_{t-1}) \in \mathcal{H}$ define $d(\vec{s})$ as follows.
Set $\lambda_i = ps_{i+1} - s_i$ ($0 \leq i \leq t-1$ subscripts mod t).
 $d(\vec{s}) = \prod_{i=0}^{t-1} d_{\lambda_i}$, where $d_k :=$ coefficient of x^k in the expansion of $(1 + x + \dots + x^{p-1})^n$
 $d(\vec{s})$ is the dimension of a $GL(n, q)$ composition factor of $\mathbb{F}_q^{\mathcal{L}_1}$.

For nonnegative integers α, β , define the subsets of \mathcal{H}

$$\mathcal{H}_\alpha(\mathbf{s}) = \left\{ (s_0, \dots, s_{t-1}) \in \mathcal{H} \mid \sum_{i=0}^{t-1} \max\{0, s - s_i\} = \alpha \right\}$$

and

$$\begin{aligned} {}_\beta\mathcal{H}(r) &= \{(n - s_0, \dots, n - s_{t-1}) \mid (s_0, \dots, s_{t-1}) \in \mathcal{H}_\beta(r)\} \\ &= \left\{ (s_0, \dots, s_{t-1}) \in \mathcal{H} \mid \sum_{i=0}^{t-1} \max\{0, s_i - (n - r)\} = \beta \right\}. \end{aligned}$$

General formula for $e_i(A_{r,1}A_{1,s})$

Theorem

Let $E_i = e_i(A_{r,1}A_{1,s})$ denote the multiplicity of p^i as a p -adic elementary divisor of $A_{r,1}A_{1,s}$.

$$E_{t(r+s)} = 1.$$

For $i \neq t(r+s)$,

$$E_i = \sum_{\vec{s} \in \Gamma(i)} d(\vec{s}),$$

where

$$\Gamma(i) = \bigcup_{\substack{\alpha+\beta=i \\ 0 \leq \alpha \leq t(s-1) \\ 0 \leq \beta \leq t(r-1)}} {}_{\beta}\mathcal{H}(r) \cap \mathcal{H}_{\alpha}(s).$$

Thank you for your attention!